#### initial

Reads input files broadcasts, and allocates/initializes global variables.

[called by: focus, globals.]

### Input namelist

The *focusin* namelist is the only input namelist needed for FOCUS running. It should be written to the file *example.input*, where 'example' is the argument passed by command line. Here are the details for the variables.

calls: .

## • IsQuiet = -1

Information displayed to the user

-2: more details & update unconstrained cost functions;

- -1: more details;
- 0: essential;
- 1: concise.

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• IsSymmetric = 0
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Enforce stellarator symmetry or not

- 0: no symmetry or periodicity enforced;
- 1: periodicty of the plasma boundary enforced;

2: periodicity and stellartor symmetry of the plasma boundary enforced.

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• input\_surf = 'plasma.boundary'

Input file containing plasma boundary information.

• input\_coils = 'none'

Input file containing initial guess for coils (in either format). If it is 'none' by default, it will be updated to 'coils.example' (case\_init=-1) or 'example.focus' (case\_init=0).

• input\_harm = 'target.harmonics'

Input file containing the target harmonics for Bmn optimization.

• limiter\_surf = 'none'

Input file containing the limiter surface for coil-surface separation.

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• case\_surface = 0

Specify the input plasma boundary format

0: general VMEC-like format (Rbc, Rbs, Zbc, Zbs), seen in rdsurf;

- 1: read axis for knots, seen in rdknot; (not ready)
- knotsurf = 0.2

Minor plasma radius for knototrans, only valid for case\_surface = 1

- ellipticity = 0.0
- Ellipticity of plasma for knototrans, only valid for case\_surface = 1
- Nteta = 64

Poloidal resolution for discretizing the plasma

• Nzeta = 64

Toroidal resolution for discretizing the plasma

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## • case\_init = 0

Specify the initializing method for coils, seen in rdcoils

- -1: read the standard MAKEGRID format coils from **input**<sub>c</sub>oils;
- 0: read FOCUS format data from input<sub>c</sub>oils;
- 1: toroidally spaced Ncoils circular coils with radius of init\_radius;
- 2: toroidally spaced Ncoils-1 magnetic dipoles pointing poloidally on the toroidal surface with radius of init\_radius and a central infinitely long current. Dipole magnetizations and the central current are all set to init\_current.
- case\_coils = 1

Specify representation used for the initial coils, seen in rdcoils

- 0: using piecewise linear representation; (not ready)
- 1: using Fourier series representation;
- Ncoils = 0

Number of coils initilized, only valid for case\_init = 1

• init\_current = 1.0E6 Initial coil current (A), only valid for case\_init = 1 • init\_radius = 1.0 Initial coil radius (m), only valid for case\_init = 1 • IsVaryCurrent = 1 Keep coil currents fixed or not, overriden by example.focus 0: coil currents are fixed; 1: coil currents are free; • IsVaryGeometry = 1 Keep coil geometries fixed or not, overriden by example.focus 0: coil geometries are fixed; 1: coil geometries are free; • NFcoil = 4Number of Fourier coefficients for coils, only valid for  $case_coils = 1$ , overriden by example focus • Nseg = 128 Number of segments for discritizing coils, only valid for case\_coils = 1, overriden by example focus • IsNormalize = 1 Normalizing coil parameters or not 0: keep raw data (normalized to 1.0); 1: currents being normalized to averaged absolute current, coil geometry parameters being normalized to major radius; • IsNormWeight = 1 each constraints normalized to initial value or not 0: keep raw value for constraints; 1:  $w = w/f_0$  weights normalized to the initial values of each constraints; • case\_bnormal = 0 Bn error normalized to |B| or not 0: keep raw Bn error; 1: Bn residue normalized to local |B|; • case\_length = 0options for constructing coil length constraint, seen in length 1: quadratic format, converging the target\_length; 2: exponential format, as short as possible; • weight\_bnorm = 1.0 weight for Bn error, if zero, turned off; seen in bnormal • weight\_bharm = 0.0 weight for Bn Fourier harmonics error, if zero, turned off; seen in bmnharm • weight\_tflux = 0.0 weight for toroidal flux error, if zero, turned off; seen in torflux • target\_tflux = 0.0 target value for the toroidal flux, if zero, automatically set to initial  $\Psi_{ave}$ ; seen in solvers • weight\_ttlen = 0.0 weight for coils length error, if zero, turned off; seen in length • target\_length = 0.0 target value (or for normalization) of the coils length, if zero, automatically set to initial actual length; seen in rdcoils • weight\_specw = 0.0 weight for spectral condensation error, if zero, turned off; seen in specwid; (not ready) • weight\_cssep = 0.0 weight for coil-surface separation constraint, if zero, turned off; seen in surfsep; • cssep\_factor = 4.0 exponential index for coil-surface separation; the higher, the steeper; seen in surfsep; • weight\_Inorm = 1.0 additional factor for normalizing currents; the larger, the more optimized for currents; seen in rdcoils • weight\_Gnorm = 1.0 additional factor for normalizing geometric variables; the larger, the more optimized for coil shapes; seen in rdcoils

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### • case\_optimize = 1

specify optimizing options.

- -2: check the 2nd derivatives; seen infdcheck; (not ready)
- -1: check the 1st derivatives; seen infdcheck;
- 0: no optimizations performed;
- 1: optimizing with algorithms using the gradient (DF, CG and/or LM); seen in solvers;
- 2: optimizing with algorithms using the Hessian (HT and/or NT); seen in solvers; (not ready)
- exit\_tol = 1.000D-04

additional creteria to judge if the cost function decreases significantly; if  $\frac{|\chi_i^2 - \chi_{i-5}^2|}{\chi_i^2} < exit_tol$ , send an exit signal; seen in solvers • DF\_maxiter = 0

maximum iterations allowed for using Differential Flow (DF); if zero, turned of; seen in descent

• DF\_xtol = 1.000D-08

relative error for ODE solver; seen in descent

• DF\_tausta = 0.000D+00

starting value of  $\tau$ ; usually 0.0 is a good idea; seen in descent

•  $DF_tauend = 0.000D+00$ 

ending value of  $\tau$ ; the larger value of  $\tau_{end} - \tau_{sta}$ , the more optimized; seen in descent

• CG\_maxiter = 0

maximum iterations allowed for using Conjugate Gradient (CG); if zero, turned of; seen in congrad

• CG\_xtol = 1.000D-08

the stopping criteria of finding minimum; if  $|d\chi^2/d\mathbf{X}| < CG_x$ tol, exit the optimization; seen in congrad;

• CG\_wolfe\_c1 = 1.000D-04

c1 value in the strong wolfe condition for line search; usually  $1.0 \times 10^{-4}$ ; seen in congrad;

• CG\_wolfe\_c2 = 0.1

c2 value in the strong wolfe condition for line search; if one CG step takes too long, try to increase c2, but remember 0 < c1 < c2 < 1; seen in congrad;

• LM\_maxiter = 0

maximum iterations allowed for using Levenberg-Marquard (LM); if zero, turned of; seen in Imalg

• LM\_xtol = 1.000D-08

the stopping criteria of finding minimum; if the relative error between two consecutivec iterates is at most xtol, the optimization terminates; seen in *lmalg*;

• LM\_ftol = 1.000D-08

the stopping criteria of finding minimum; if both the actual and predicted relative reductions in the sum of squares are at most ftol, the optimization terminates; seen in *lmalg*;

• LM\_factor = 1.000D+02

factor is a positive input variable used in determining the initial step bound. this bound is set to the product of factor and the euclidean norm of diag\*x if nonzero, or else to factor itself. in most cases factor should lie in the interval (0.1,100.0). 100 is a generally recommended value. seen in *lmalg*;

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# • case\_postproc = 1

specify post-processing options.

- 0: no extra post-processing;
- 1: evaluate the present coils for each cost functions, coil curvature, coil-coil separation, and coil-plasma separation, Bn harmonics overlap, coil importance;
- 2: diagnos; write SPEC input file;
- 3: diagnos; Field-line tracing, axis locating and iota calculating;
- 4: diagnos; Field-line tracing; Calculates Bmn coefficients in Boozer coordinates;
- 5: diagnos; write mgrid file (input variables in the namelist &mgrid);
- update\_plasma = 0

if euqals 1, write example.plasma file with updated Bn coefficients;

- pp\_phi = 0.0
  - Toroidal angle  $\phi = pp_phi * \pi$  for filed-line tracing, axis locating, etc.
- pp\_raxis = 0.0
- pp\_zaxis = 0.0

Initial guess for axis positions (raxis, zaxis). If both zero, will be overide to  $(\frac{r_1+r_2}{2}, \frac{z_1+z_2}{2})$ , where  $r_1 = R(0, \phi)$ ,  $r_2 = R(\pi, \phi)$  (likewise for  $z_1, z_2$ .)

pp.rmax = 0.0 pp.rmax = 0.0 Upper bounds for field-line tracing. If both zero, will be overide to (r<sub>1</sub>, z<sub>1</sub>).
pp.ns = 10 Number of surfaces for filed-line tracing, axis locating, etc. Starting points on \$\phi\$ will be interpolated between (r<sub>axis</sub>, z<sub>axis</sub>) and (r<sub>max</sub>, z<sub>max</sub>).
pp.maxiter = 1000 Cycles for tracing the field-line, representing the dots for each field-line in Poincare plots.
pp.tol = 1.0E-6 Tolerance of ODE solver used for tracing field-lines.
save\_freq = 1 frequency for writing output files; should be positive; seen in solvers;
save\_coils = 0 flag for indicating whether write example.focus and example.coils; seen in saving;
save\_harmonics = 0

flag for indicating whether write example.harmonics; seen in saving;

• save\_filaments = 0

flag for indicating whether write .example.filaments.xxxxx; seen in saving;

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Focus subroutines;