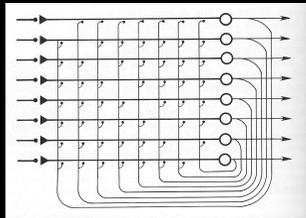
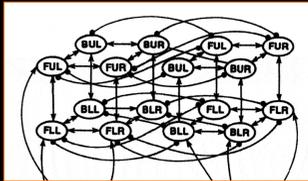


Associative Learning and Feature Maps

Learning

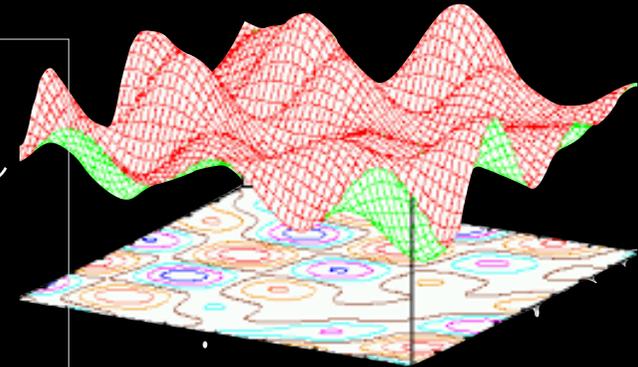
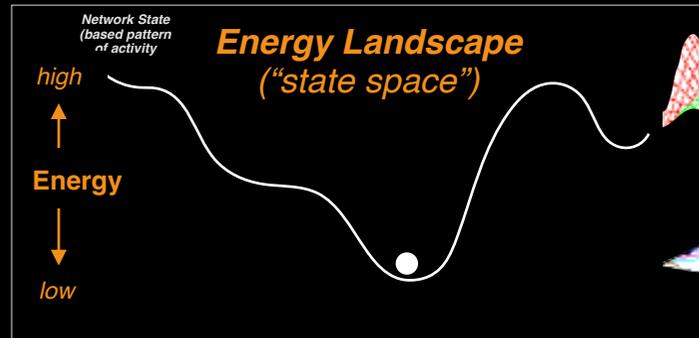
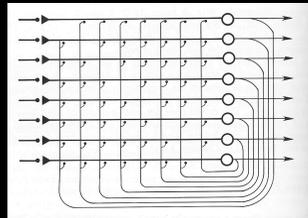
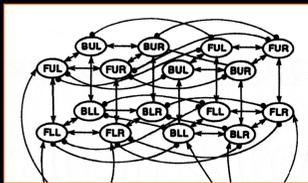
Learning

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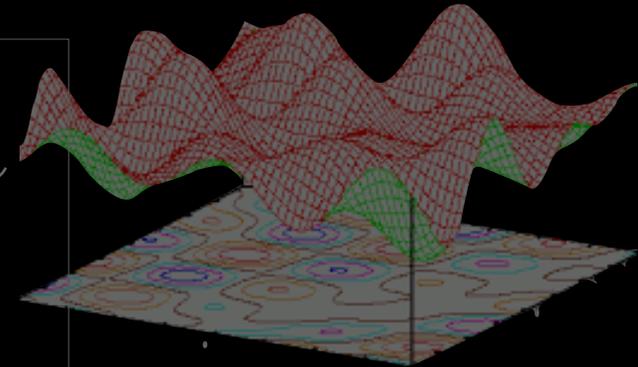
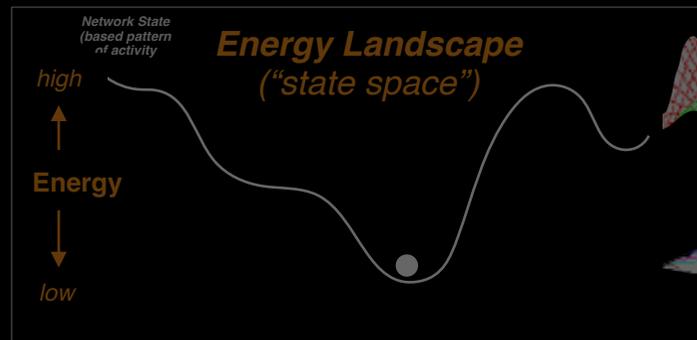
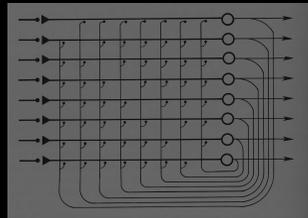
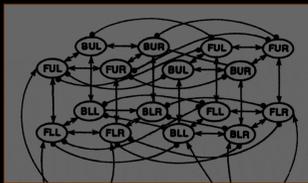
Learning

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 - dynamics of *processing*: encoding and representation information



Learning

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- What about learning?
 - how is the landscape shaped?
 - dynamics of *acquisition*

Learning



- **Unsupervised Learning**

- Hebbian Learning Rule
- Self-organized maps
- Topographic structure
- Pattern associator
- Pattern detectors

- **Supervised Learning**

- **Scalar Learning**
 - Classical and Instrumental Conditioning
 - Sequential learning and Prediction
- **Vector-Based Learning**
 - Generalized Delta Rule
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- **Fundamental learning mechanism**

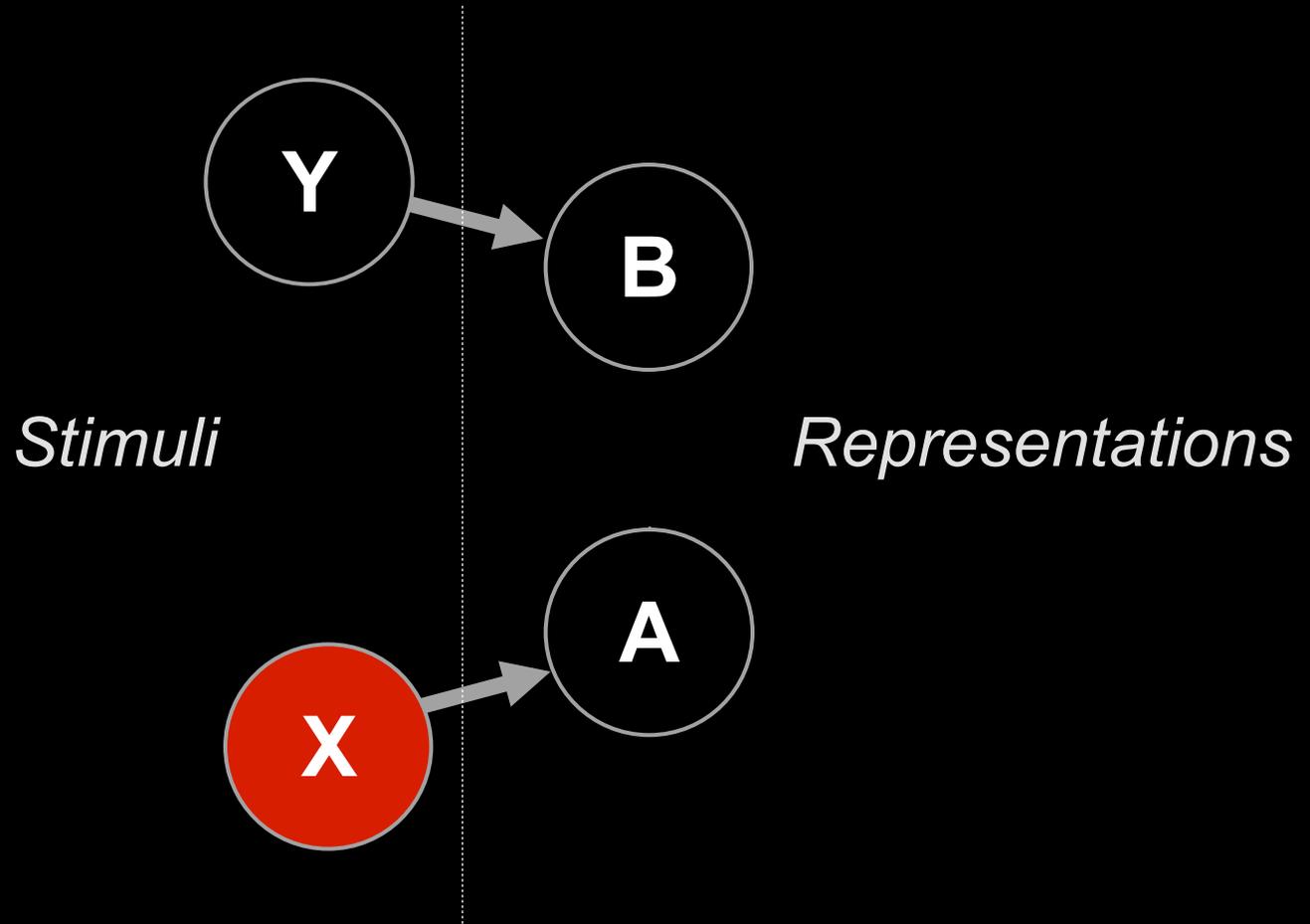
- responsible for much of how we gain our knowledge

Hebbian Learning

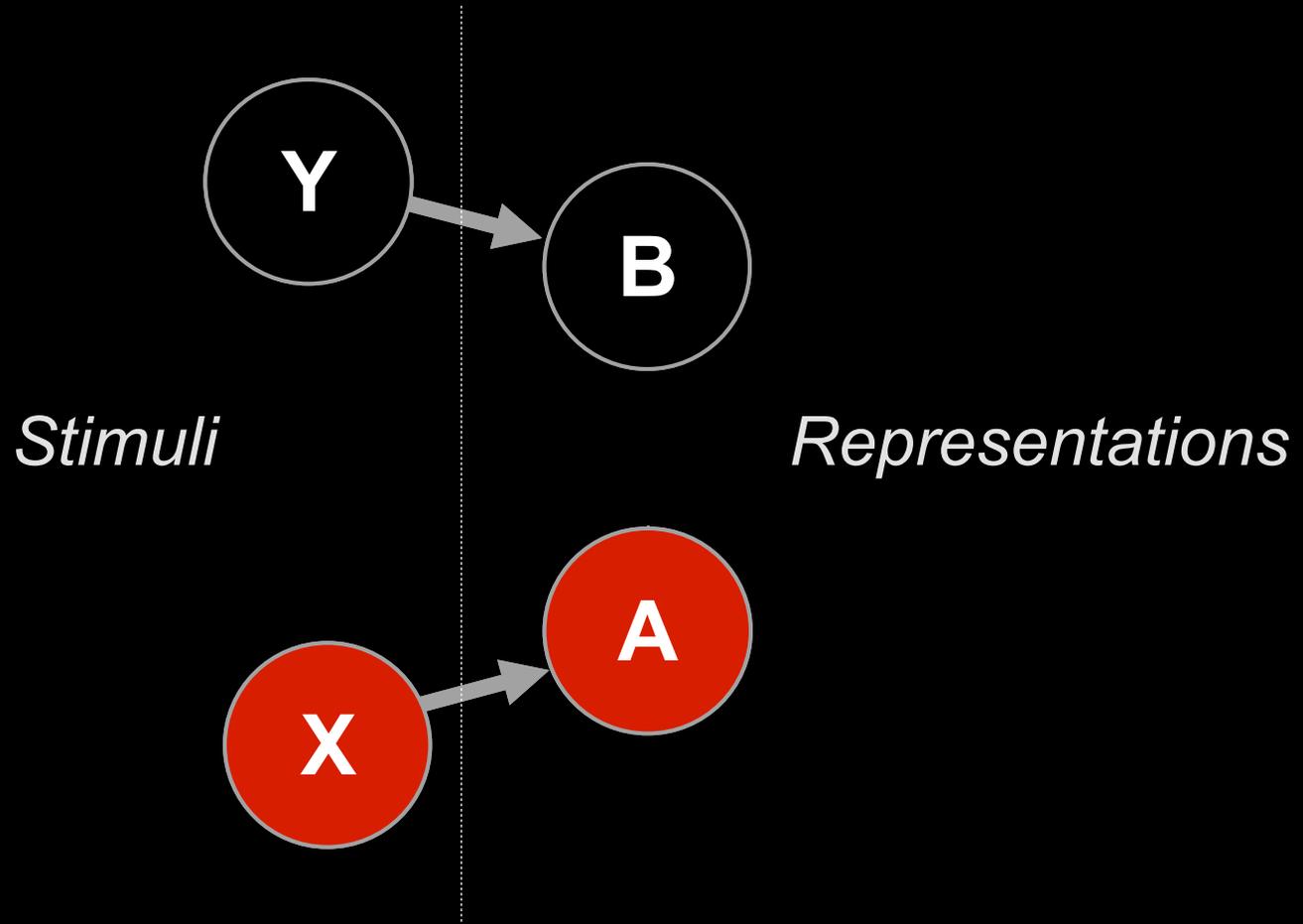
Stimuli

Representations

Hebbian Learning

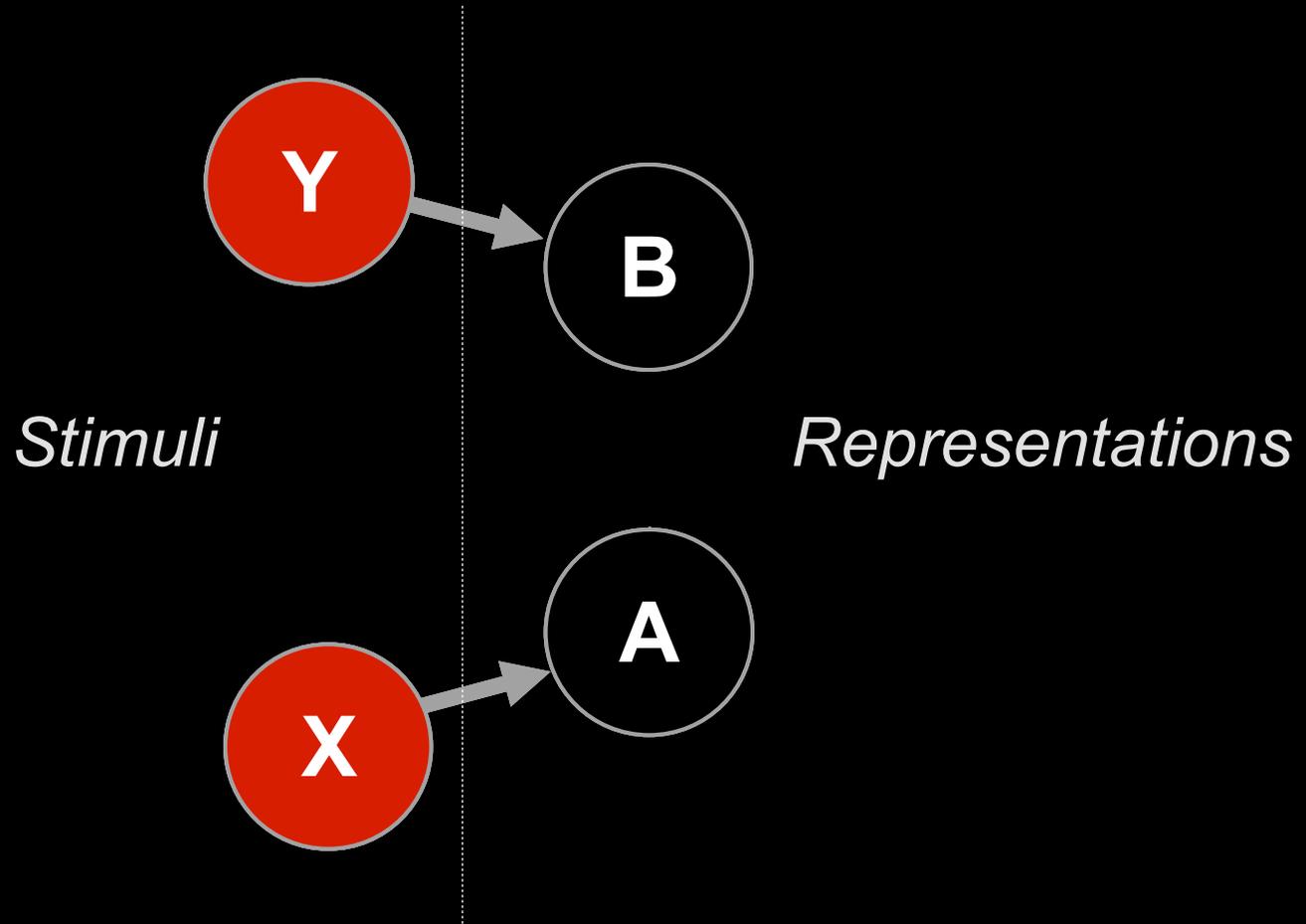


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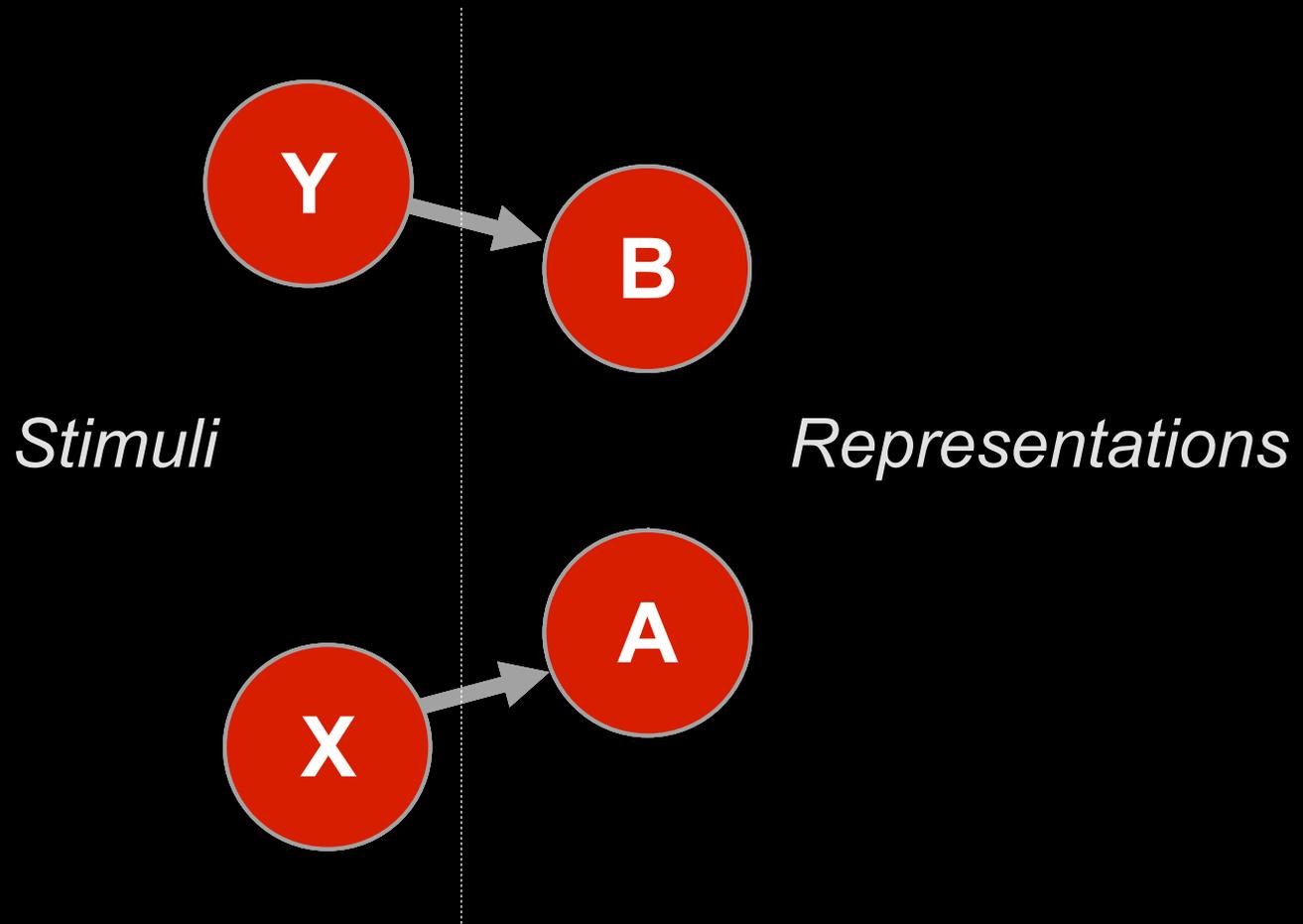
X activates A but not B

Hebbian Learning



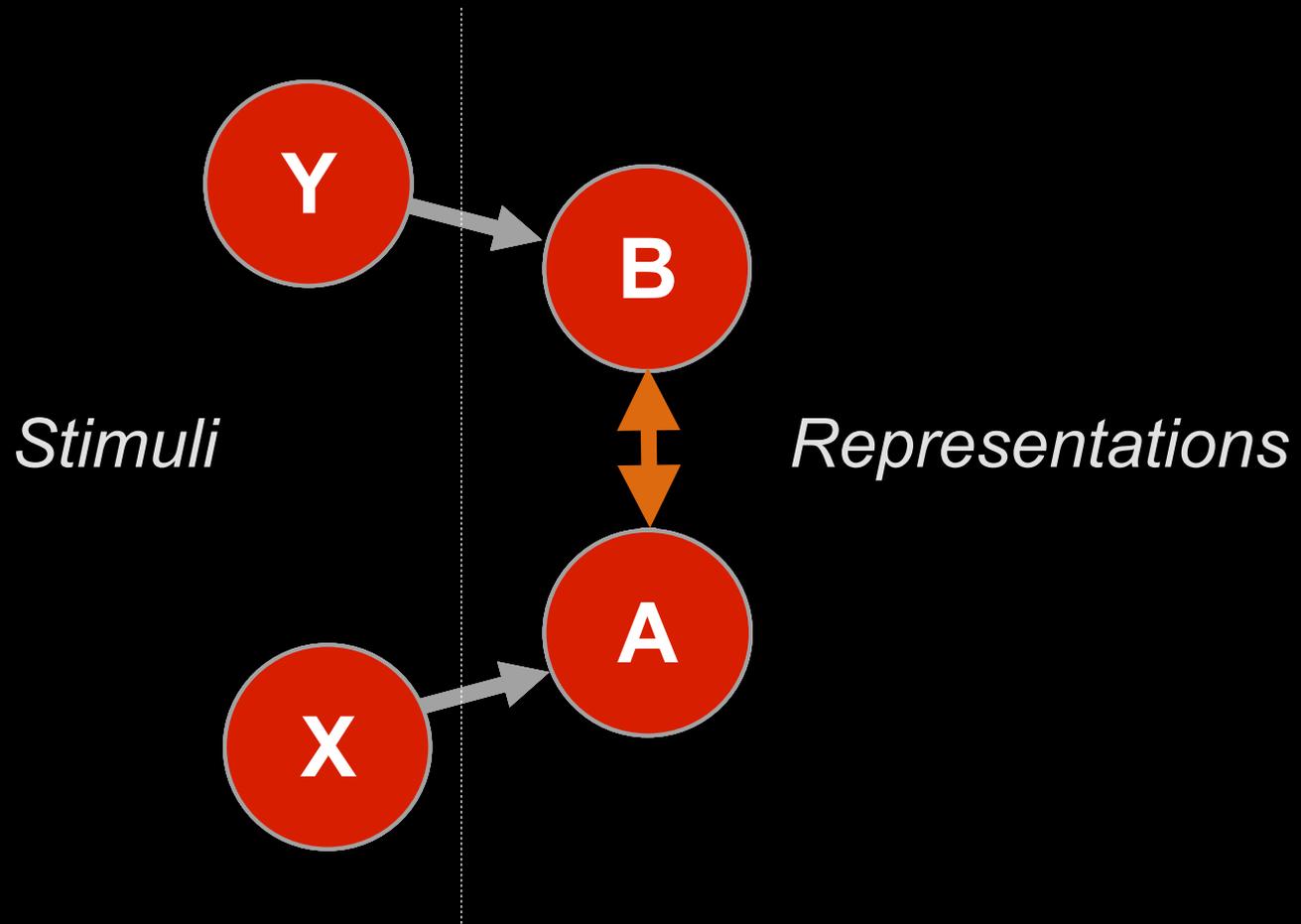
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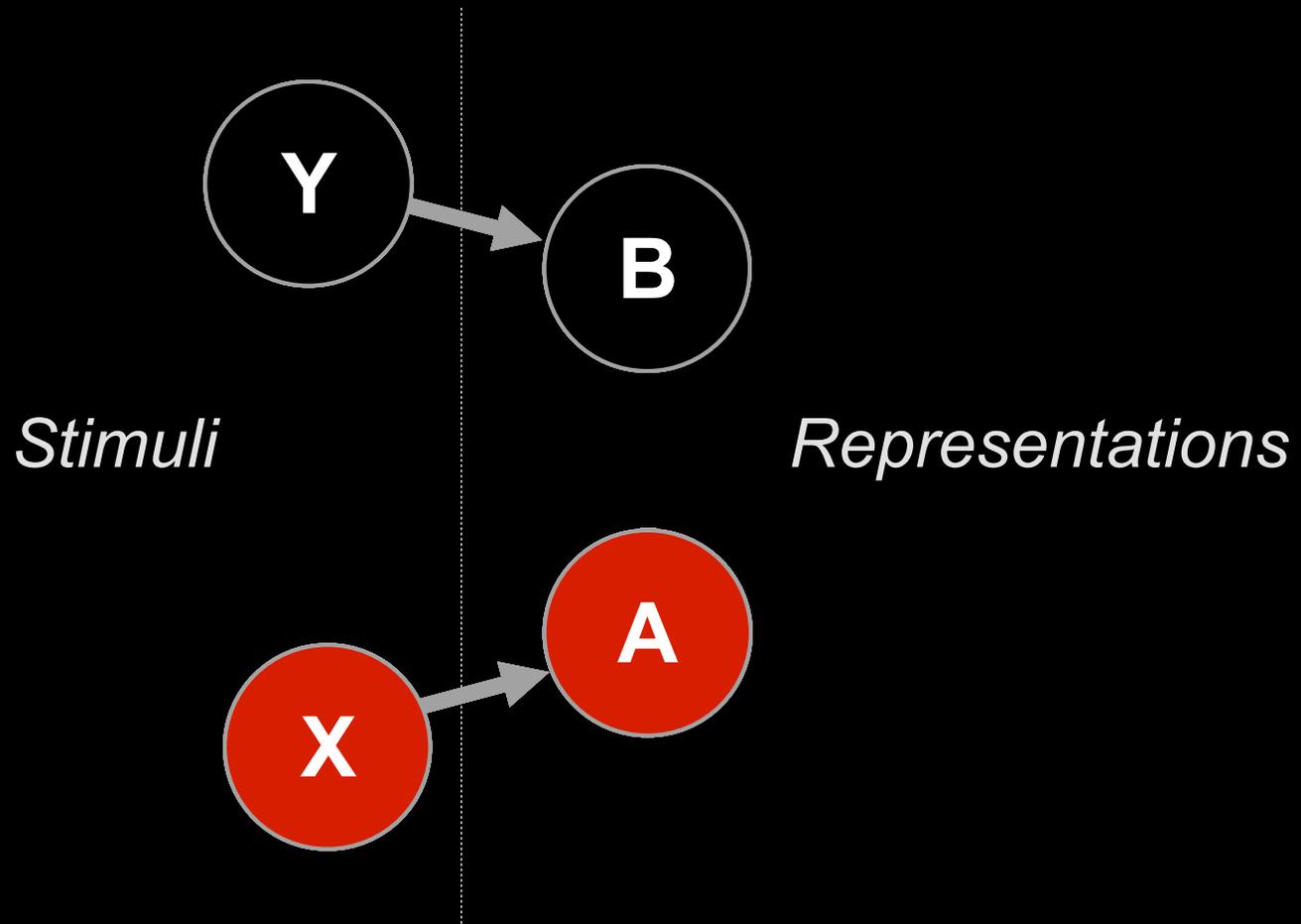
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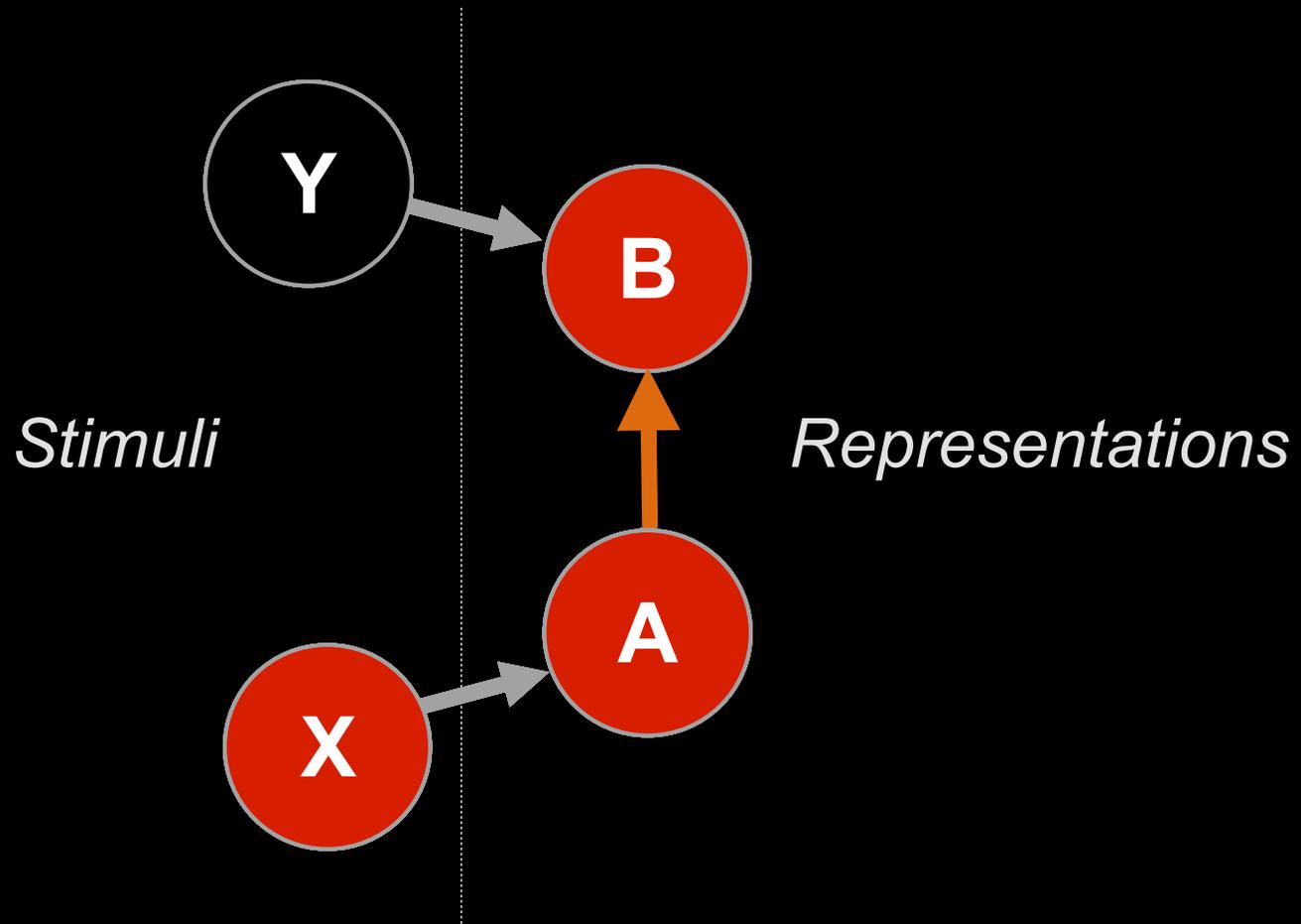
...which strengthens connection between A and B

Hebbian Learning



Activating X activates A *which now activates B*

Hebbian Learning



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Formalism:

$$\Delta w_{ij} = \alpha a_i a_j$$

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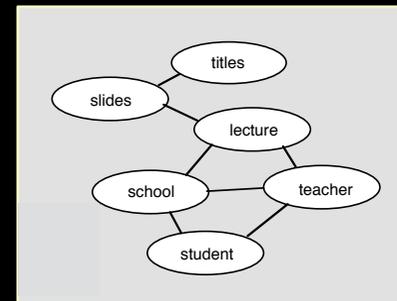
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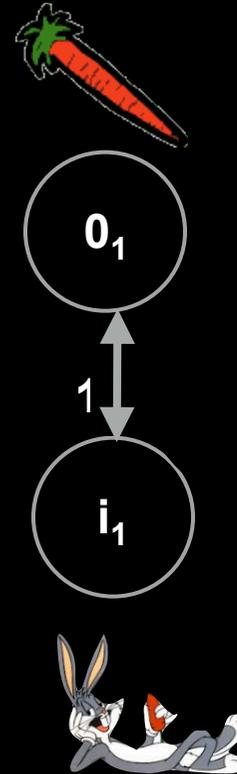
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Captures statistical relationship among co-occurring features

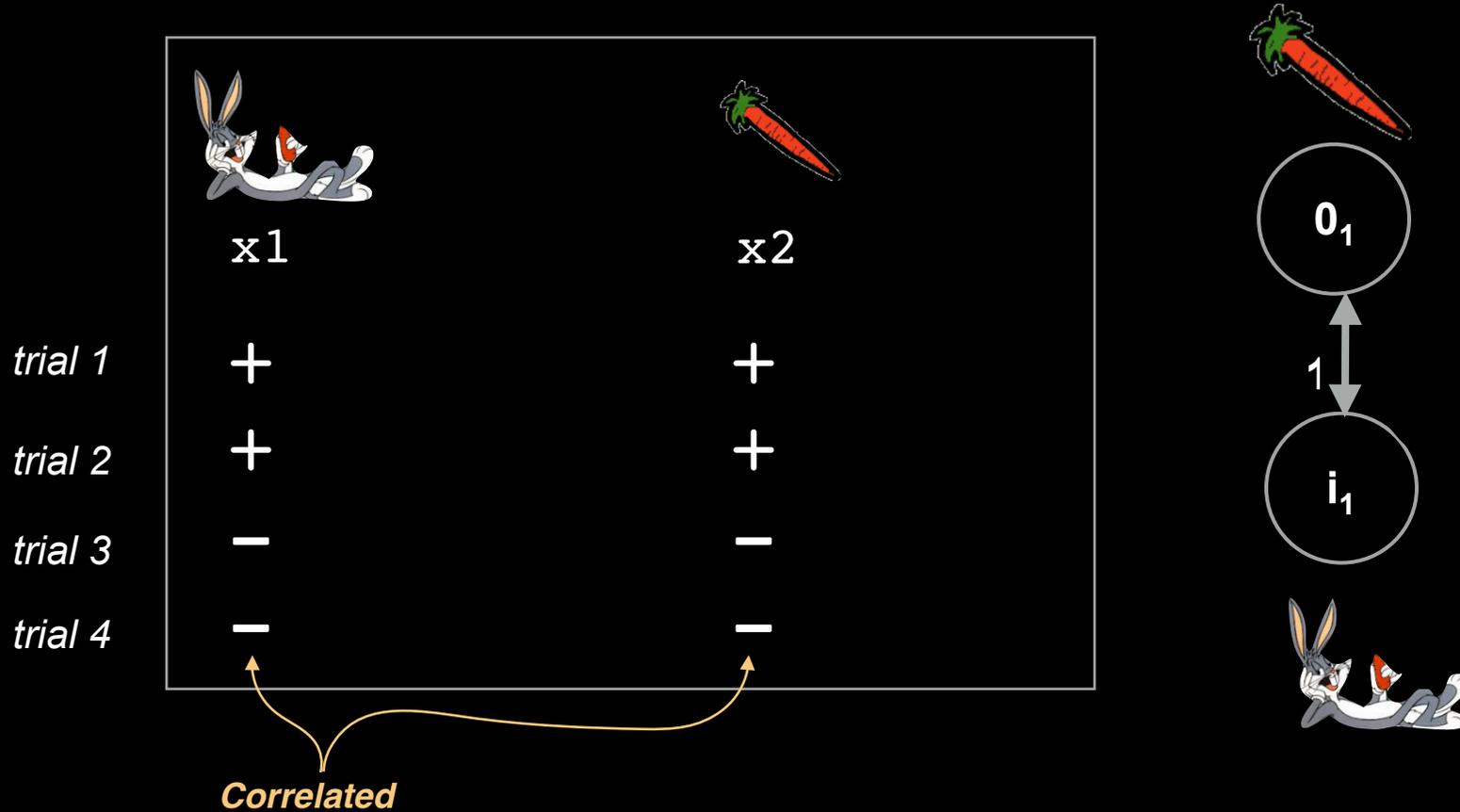


Multiple Associations

	 x1	 x2
<i>trial 1</i>	+	+
<i>trial 2</i>	+	+
<i>trial 3</i>	-	-
<i>trial 4</i>	-	-



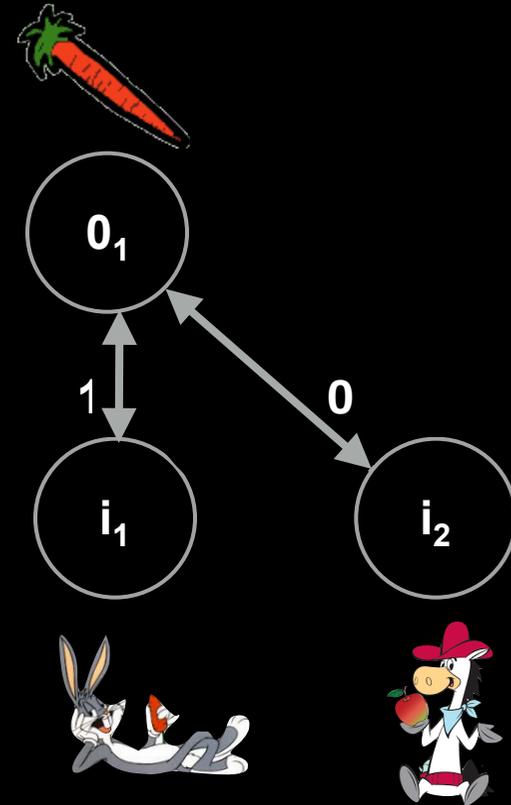
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Multiple Associations

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trial 1	+	+	+
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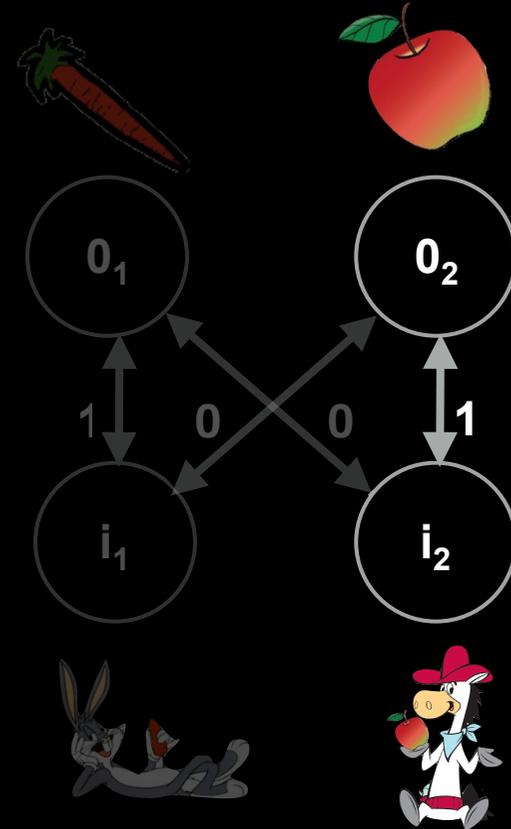
Correlated *Uncorrelated*



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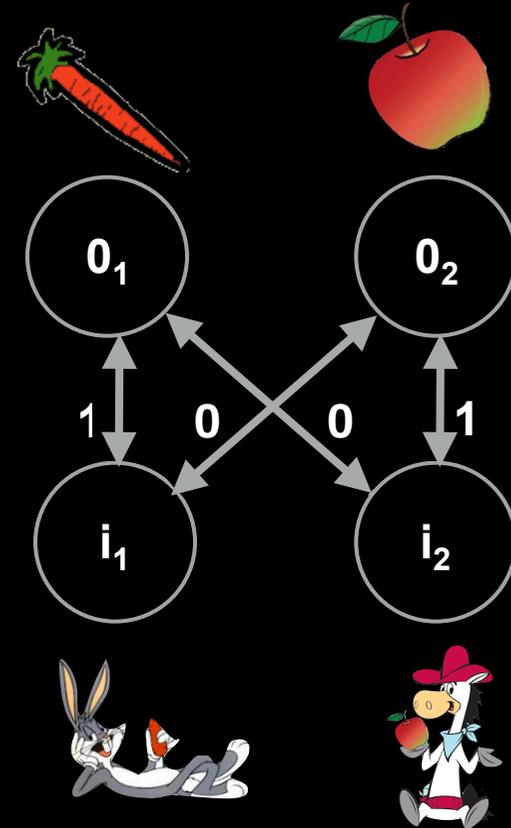
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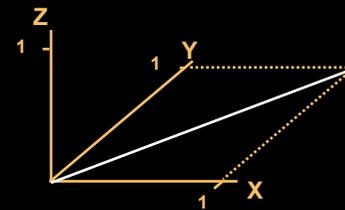
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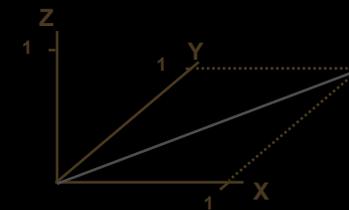
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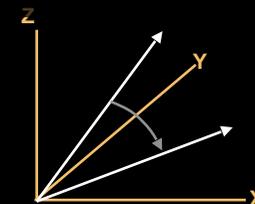
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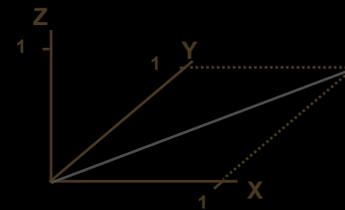
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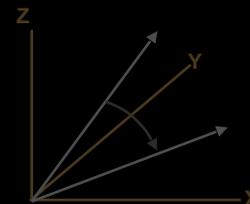
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- **Two patterns whose NDP = 0 are said to be “orthogonal”**

- ♦ *Tip: Vectors that are “perpendicular” in 3D space are orthogonal (compute the NDP for the x axis against the y axis); this is because they are uncorrelated*

Associative Learning and Internal Representations / Model Building

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More Generally...

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- **Parameterization implements different classes of statistical functions**

Various Approaches

- **Pattern associator**
 - Inputs + detector units -> network implementation of Principal Components Analysis (PCA)
- **Linsker's Information Maximization**
 - Multiple detector units, similar to PCA network:
maximizing variance in output units \approx maximizing information
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 - Multiple detector units with structured local connections among them:
captures neighborhood relationships among features; topographic maps
(Ken Miller's simulations of ocular dominance columns)
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 - Exploited for imaging (e.g., *retinotopic mapping of primary visual cortex*)
 - Even as it gets more complex, some topography is maintained:
 - ♦ Occular dominance columns (Miller, 1989)
 - ♦ Orientation and retinotopic position “pinwheels” (Durbin & Mitchison, 1990)

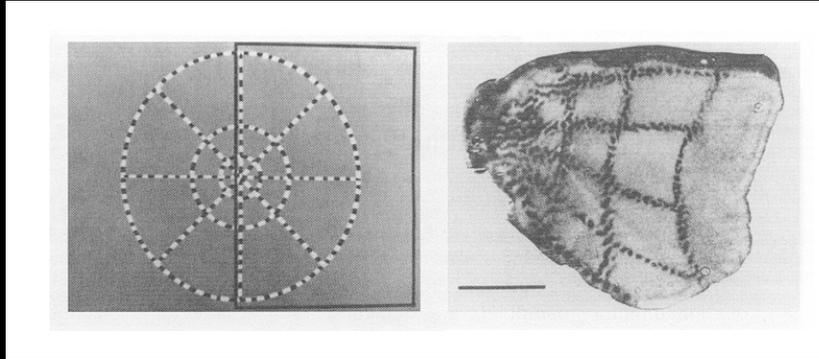


Topographic Organization

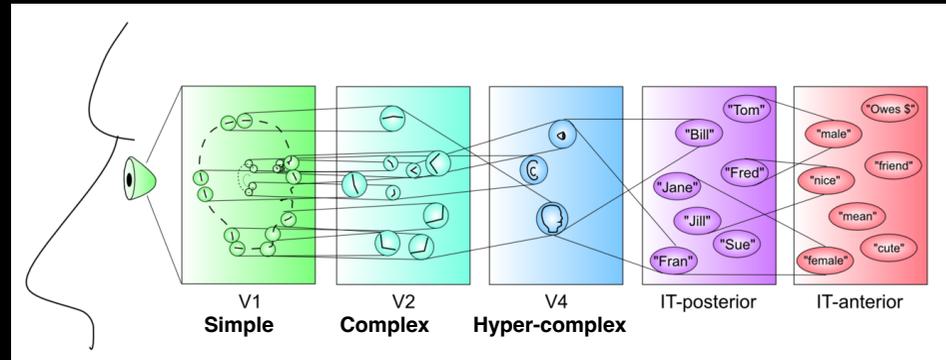
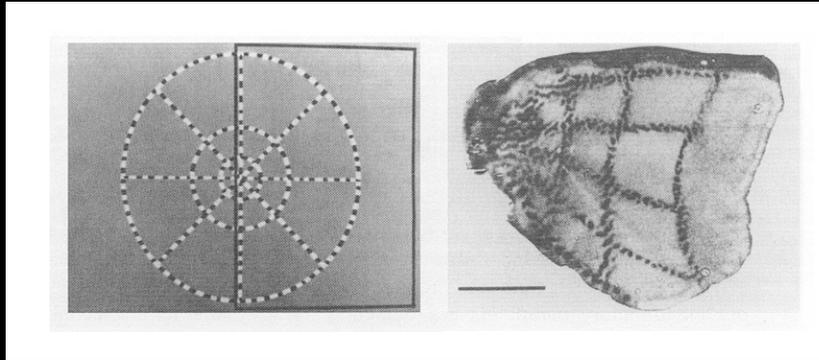
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- These may reflect meaningful relationships that exist in the “data” (*i.e.*, the “real world”)

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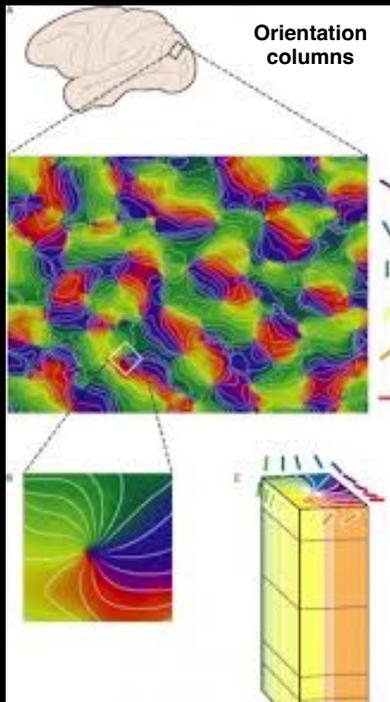
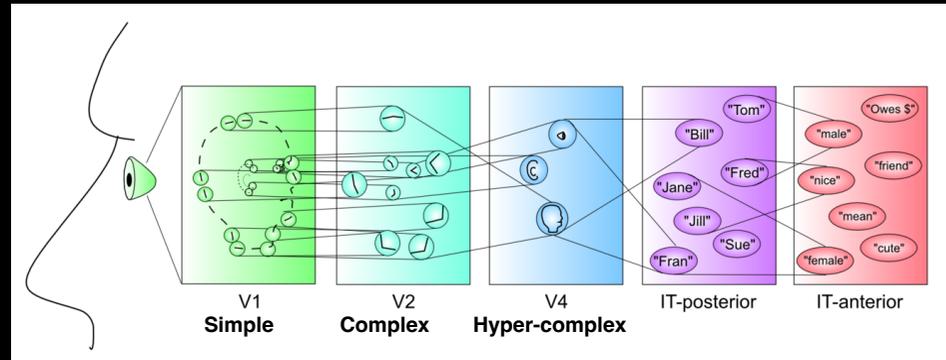
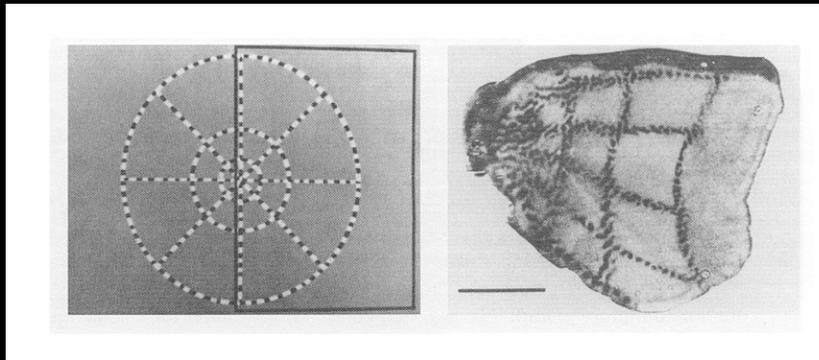
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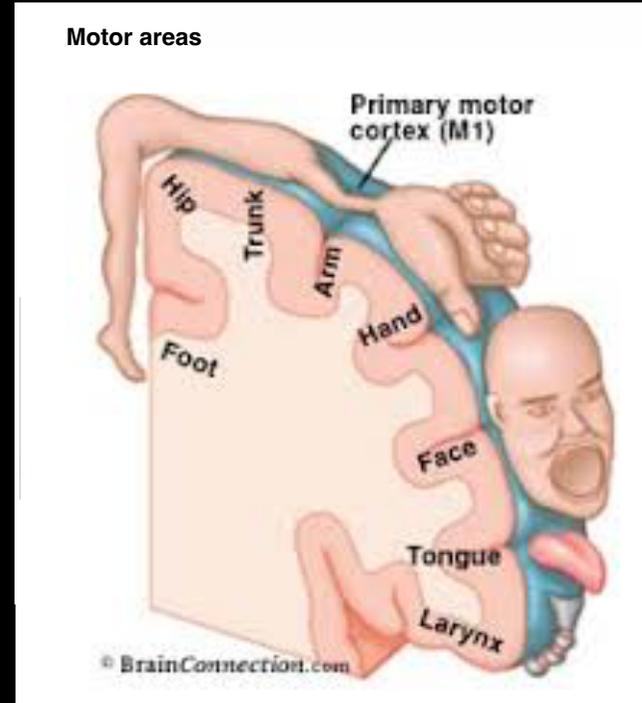
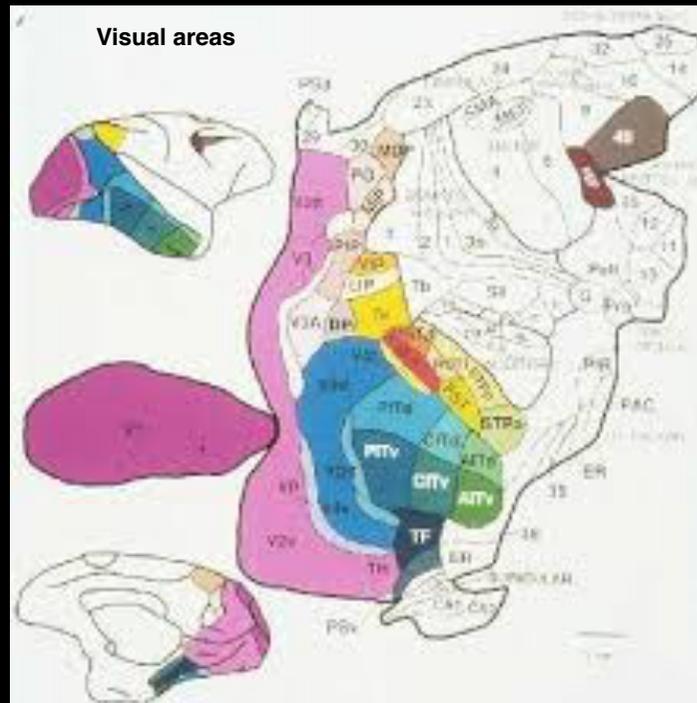
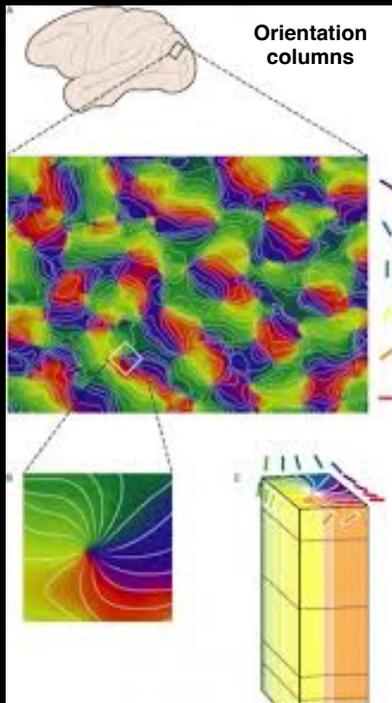
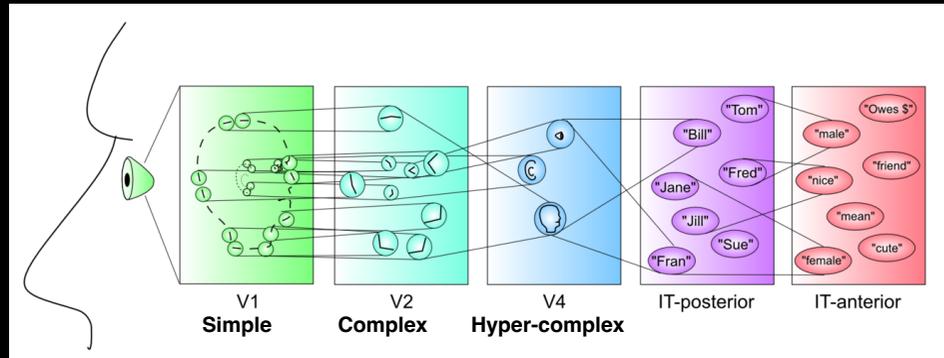
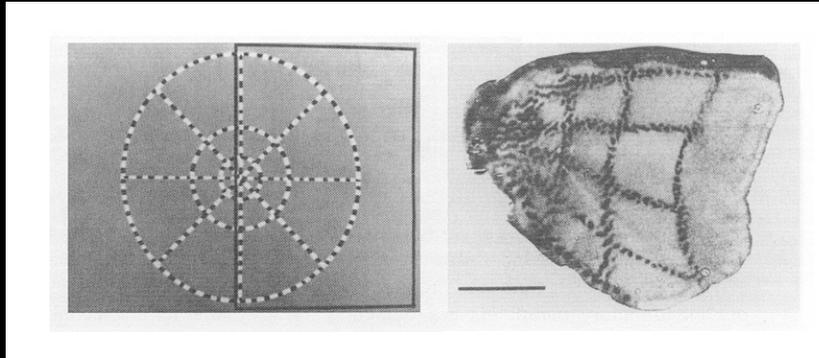
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“Dimension Reduction”

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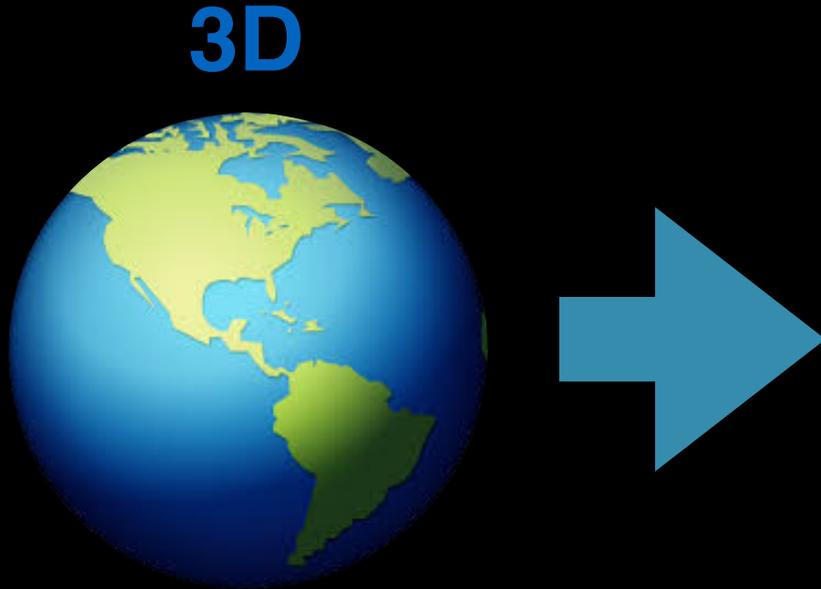
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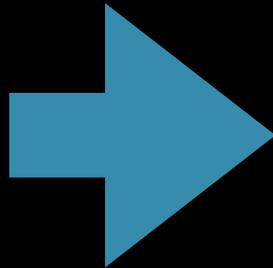
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3D

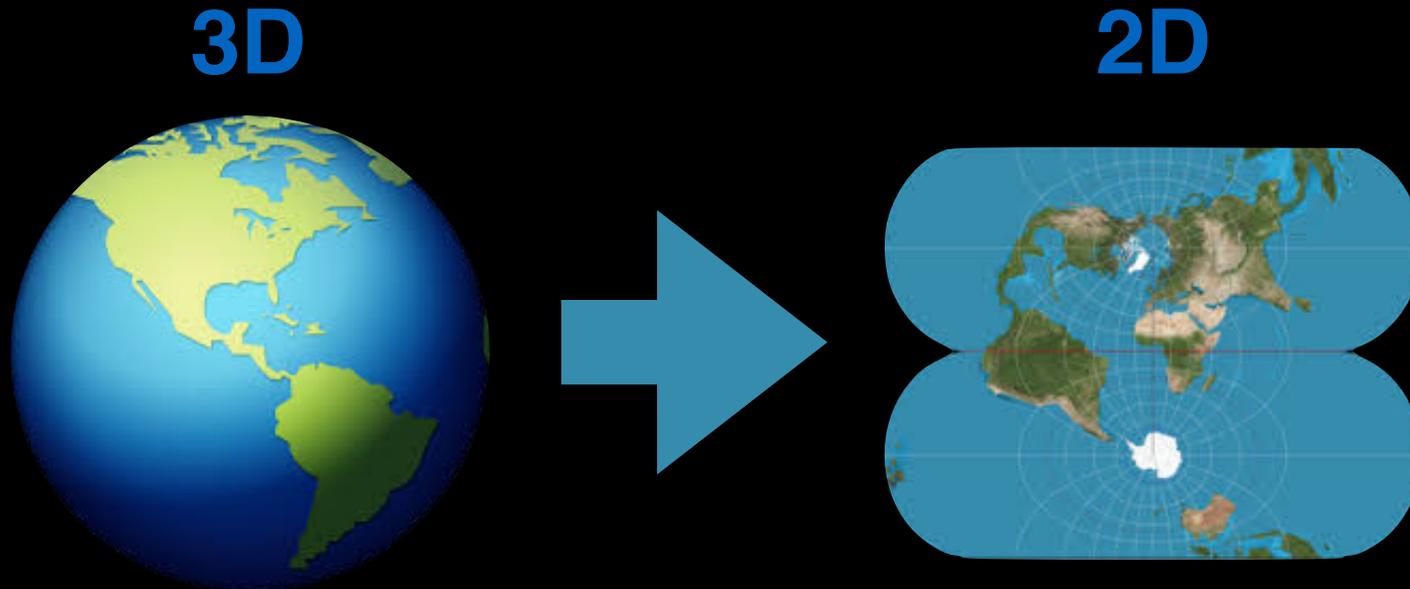


2D



“Dimension Reduction”

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- What about even higher dimensional data?

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- Objectives:

- Map input vectors (patterns) of dimension N onto a map with 1 or 2 dimensions.
- Patterns *close* to one another in the input space should project to *nearby* units (“map” should be *topographically ordered*)

Self-Organizing Maps (SOMs)

Kohonen Network (1982)

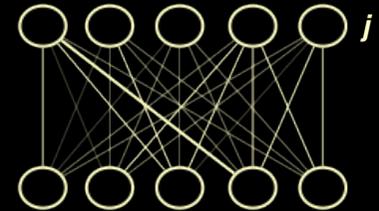
- Objectives:
 - Map input vectors (patterns) of dimension N onto a map with 1 or 2 dimensions.
 - Patterns *close* to one another in the input space should project to *nearby* units (“map” should be *topographically ordered*)
- Network architecture and input environment (“training”)
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 - ♦ units that code a space of *vectors with structure*, but *not spatially arranged*



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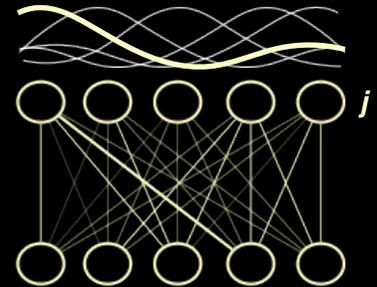
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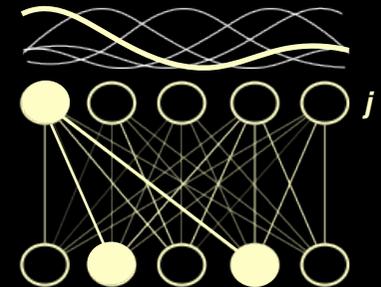
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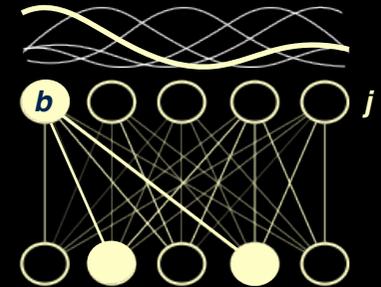
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$$W_{b(t+1)} = W_{b(t)} + c_{wb(t)} \cdot g(t) \cdot (I - W_{b(t)})$$

change in weights to b closeness to b gain difference from Input pattern

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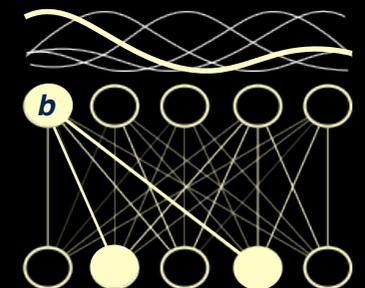
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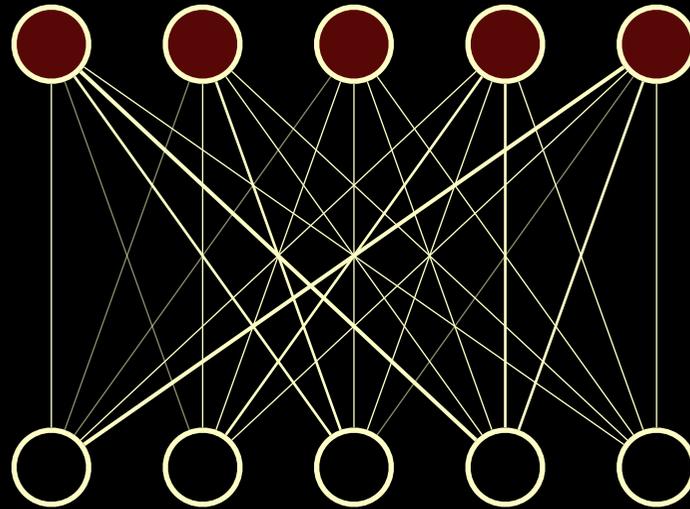
difference from Input pattern

α correlation of output unit with pattern of activity over input units

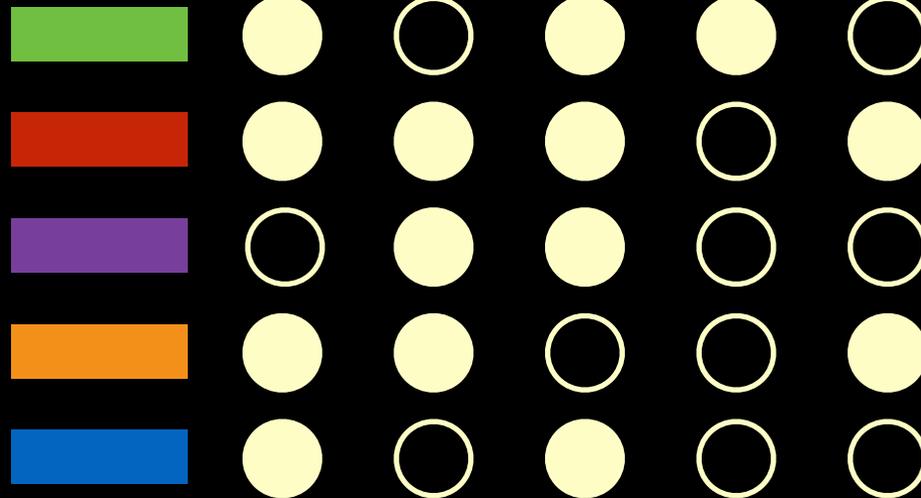
Self-Organizing Maps

Network

*Small random
initial weights*

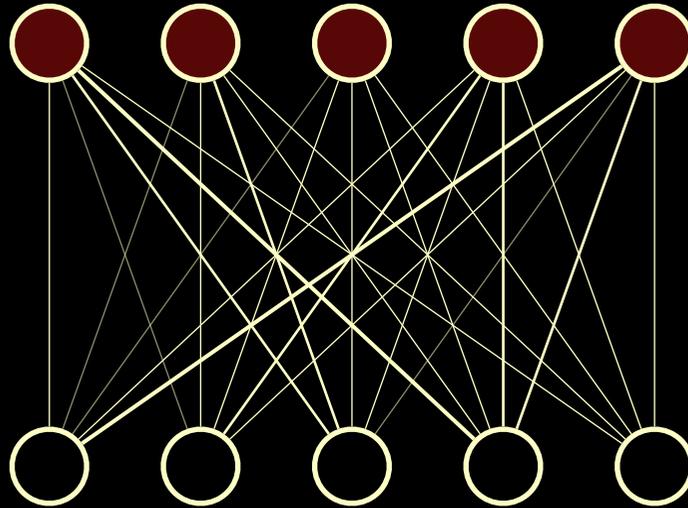


**Input
Patterns**



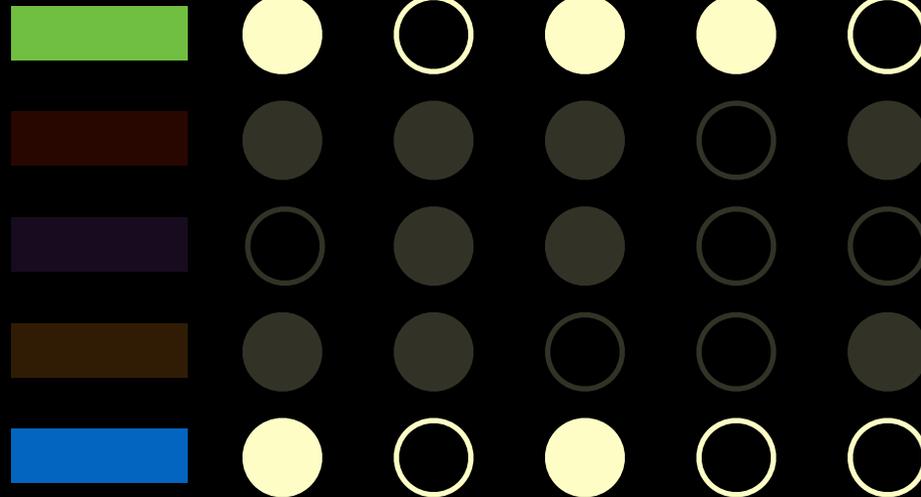
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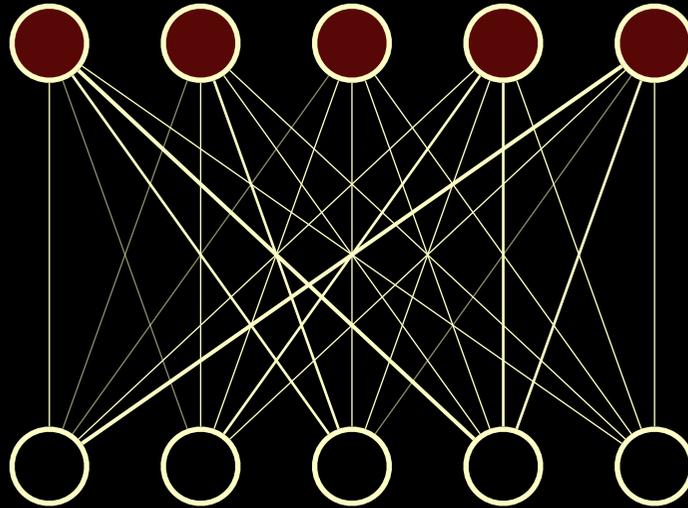
**Input
Patterns**



*Similar colors
have similar patterns*

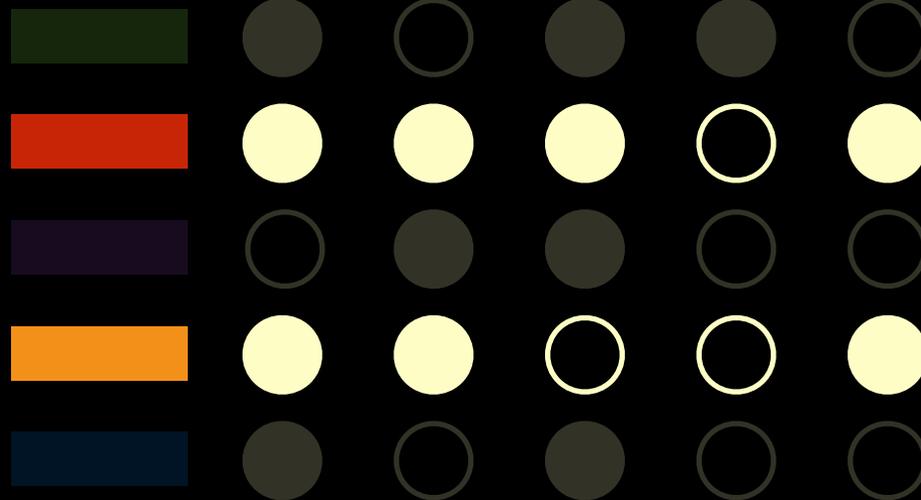
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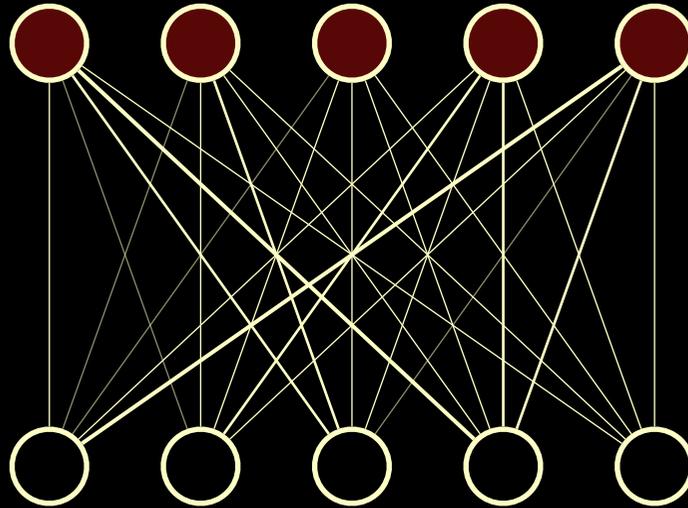
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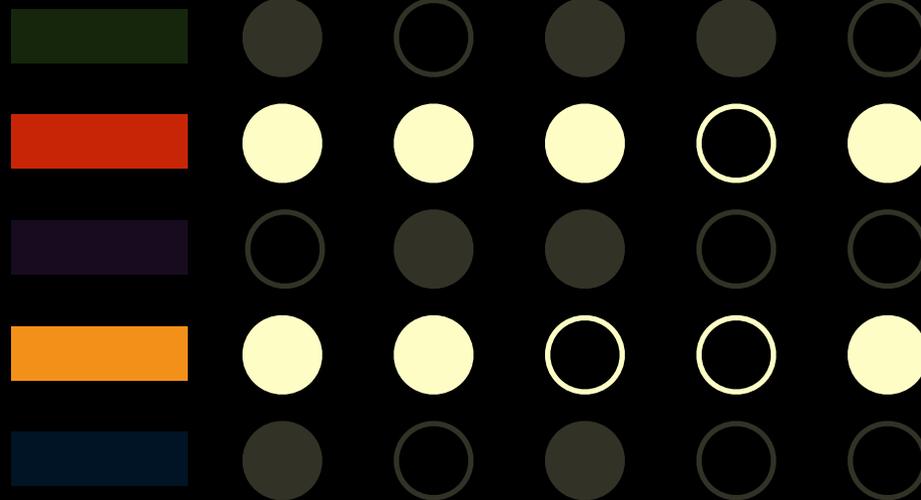
Self-Organizing Maps

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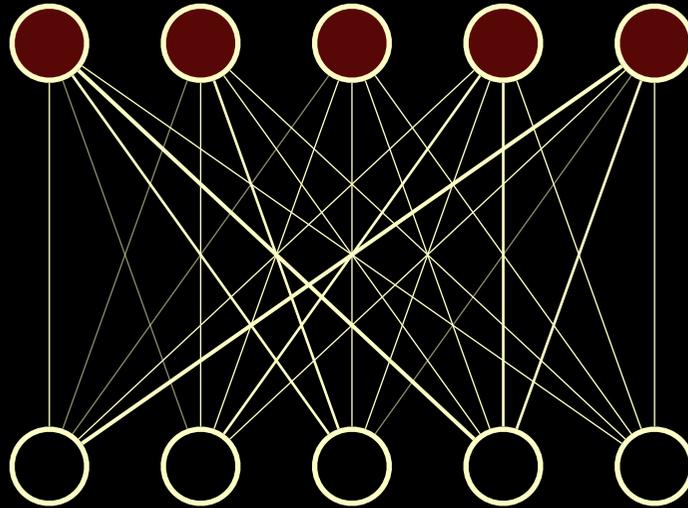


*Similar colors
have similar patterns*

*But without
spatial ordering*

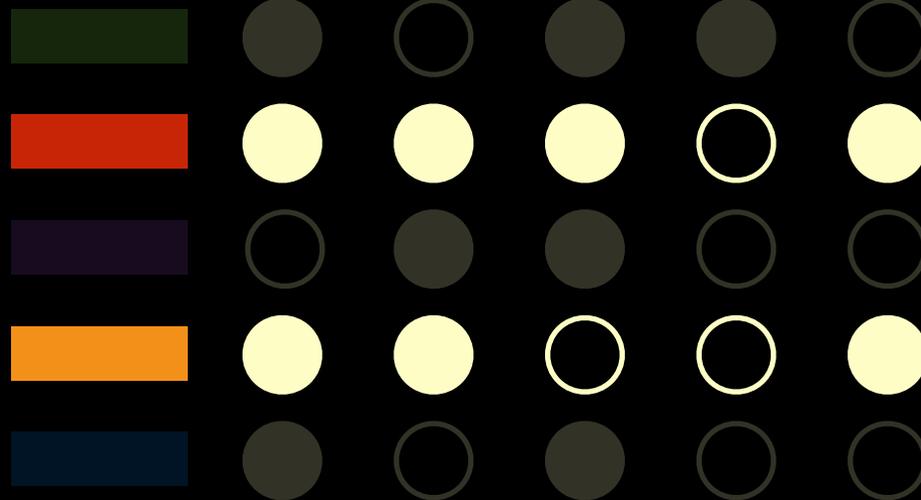
Self-Organizing Maps

Network



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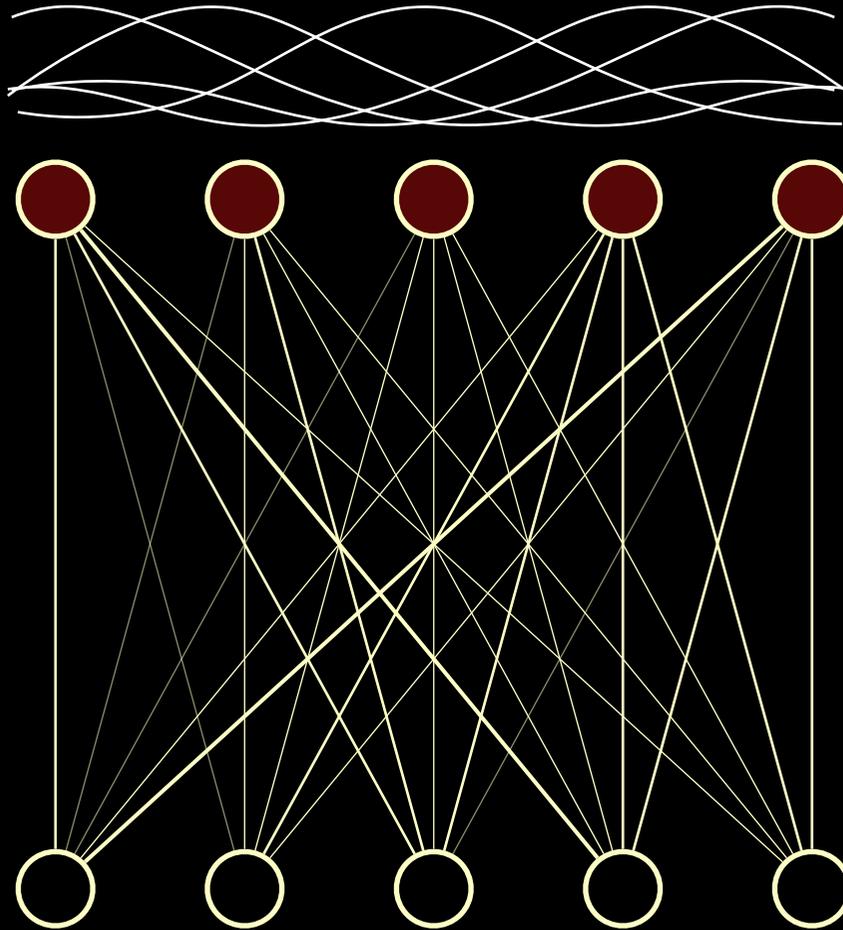
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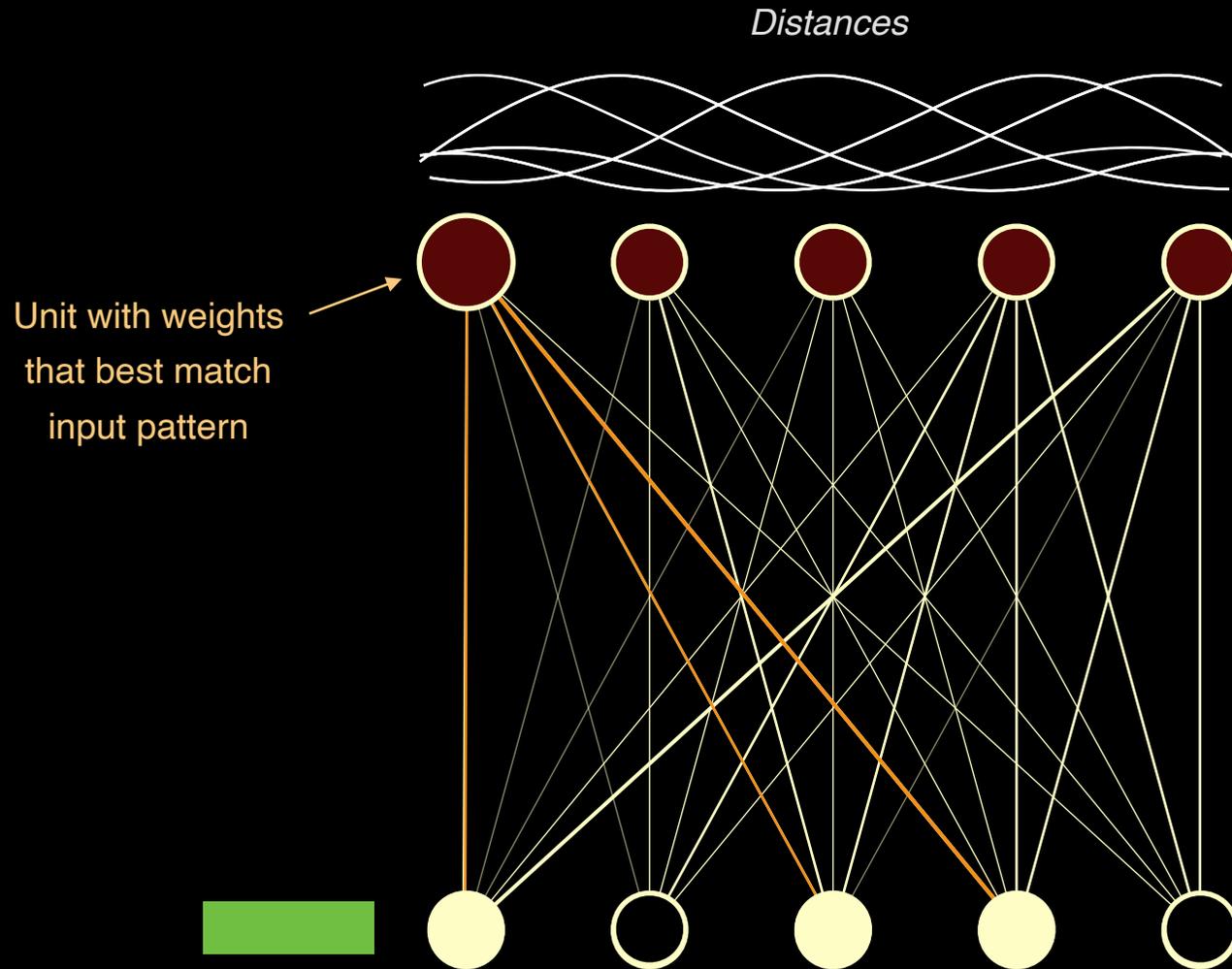
Demo

Self-Organizing Maps

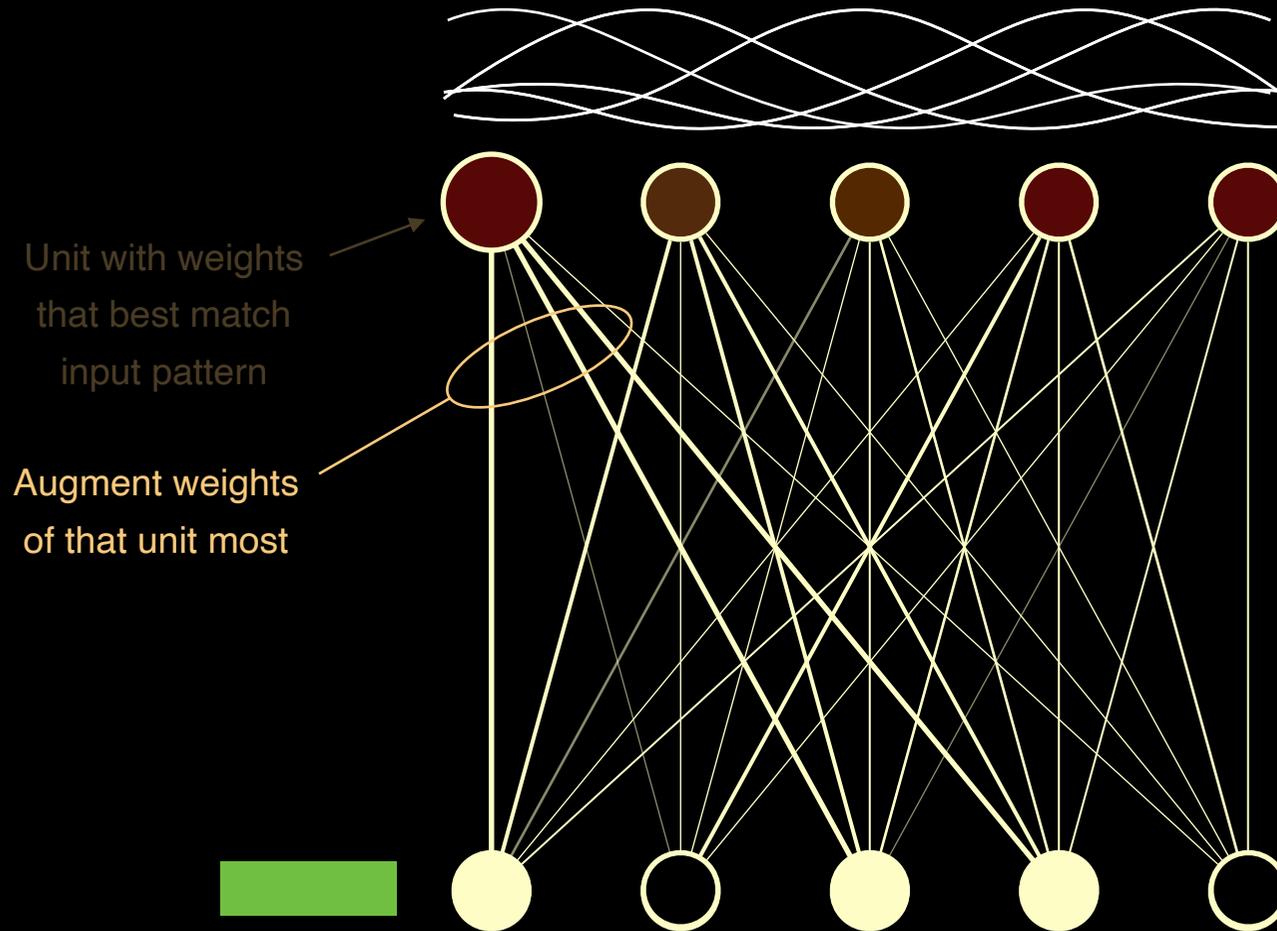
Distances



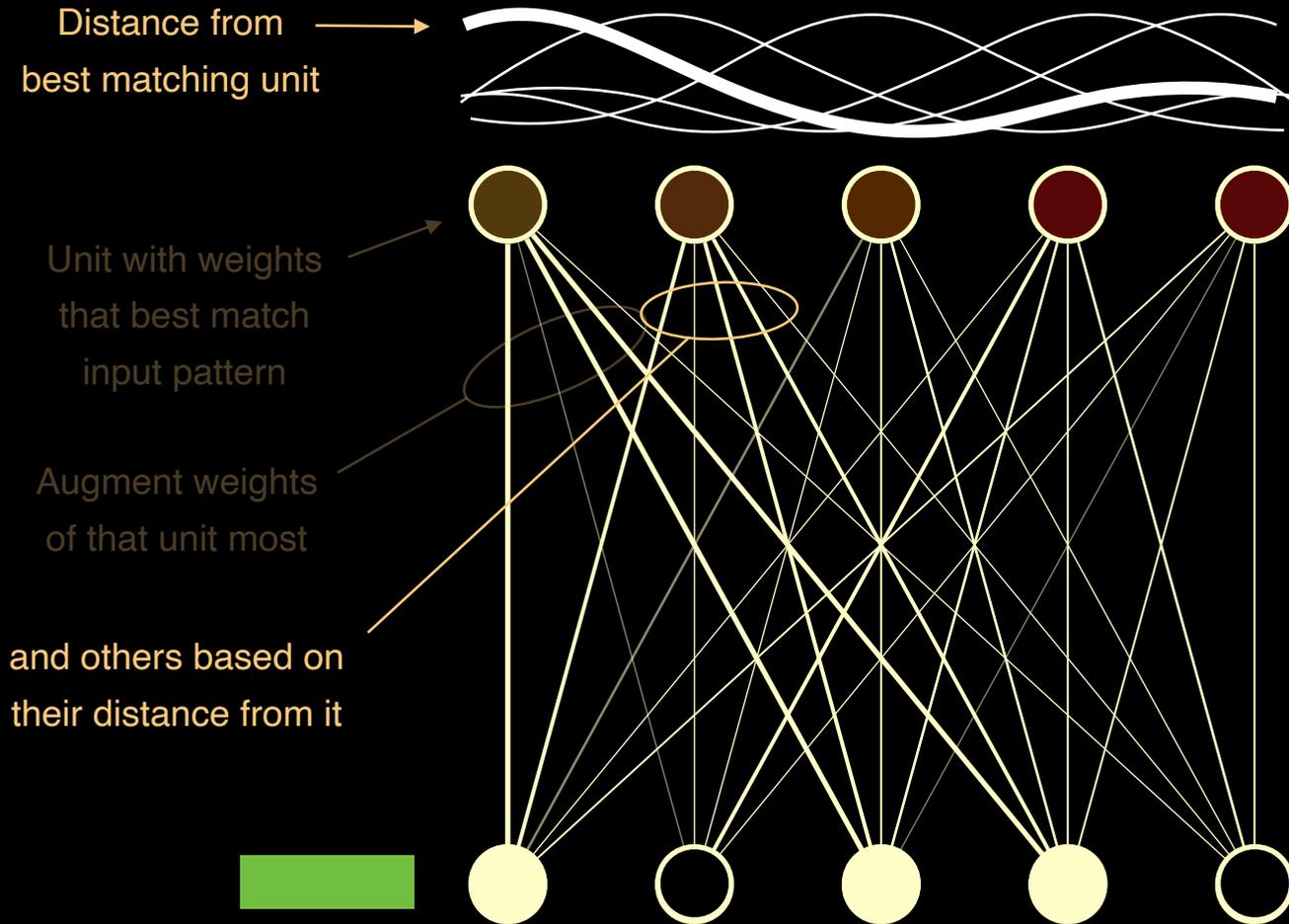
Self-Organizing Maps



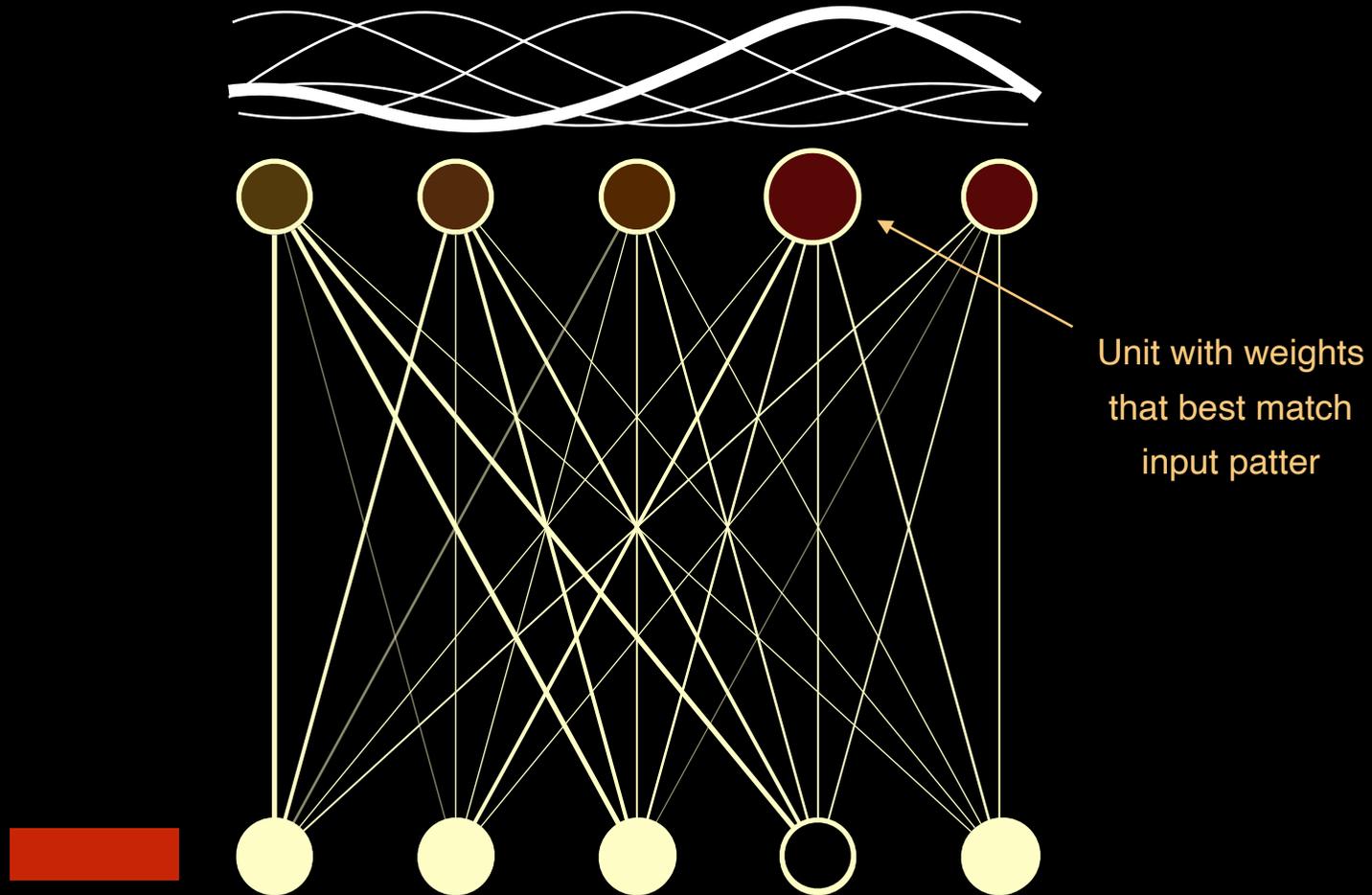
Self-Organizing Maps



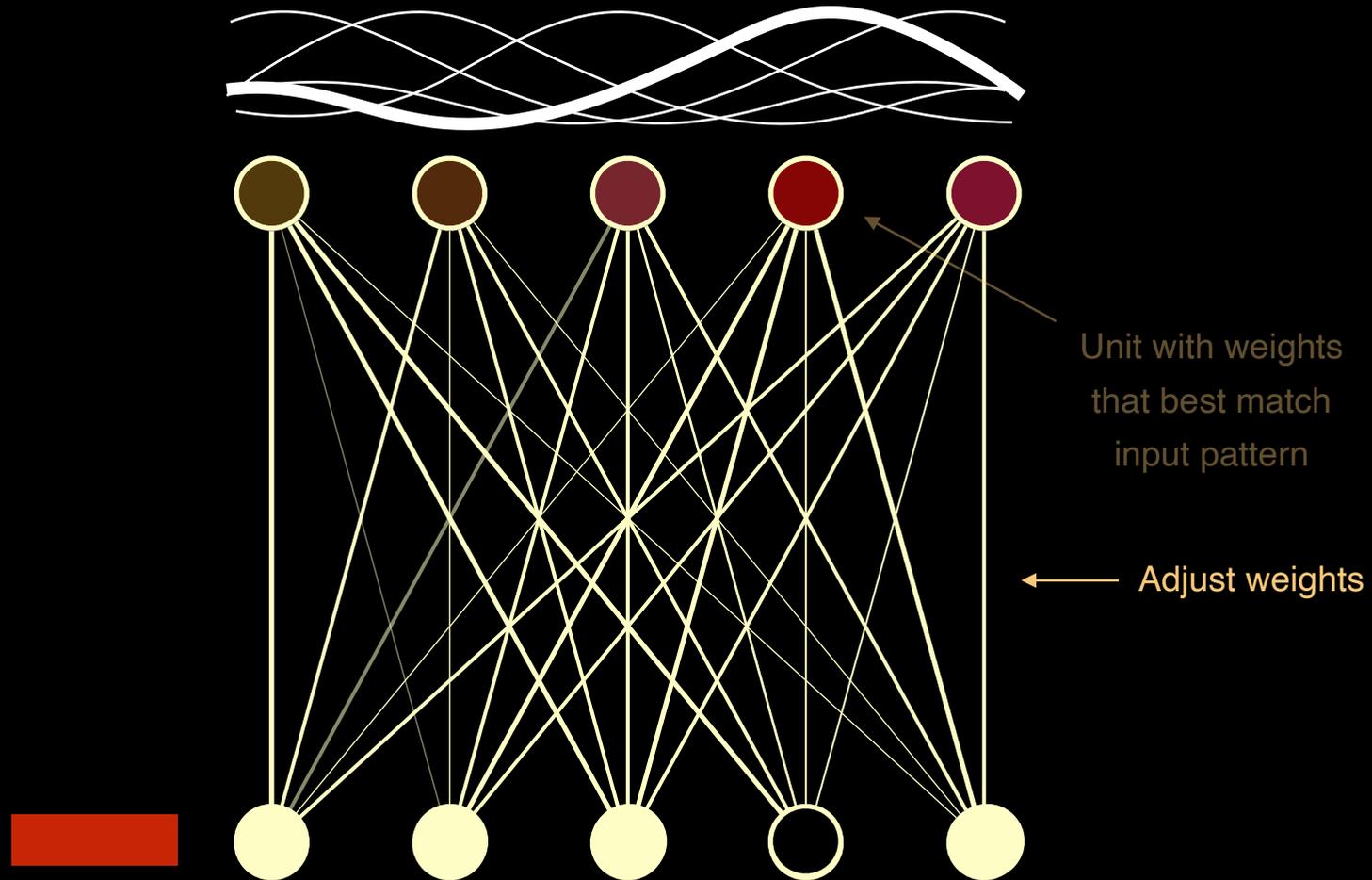
Self-Organizing Maps



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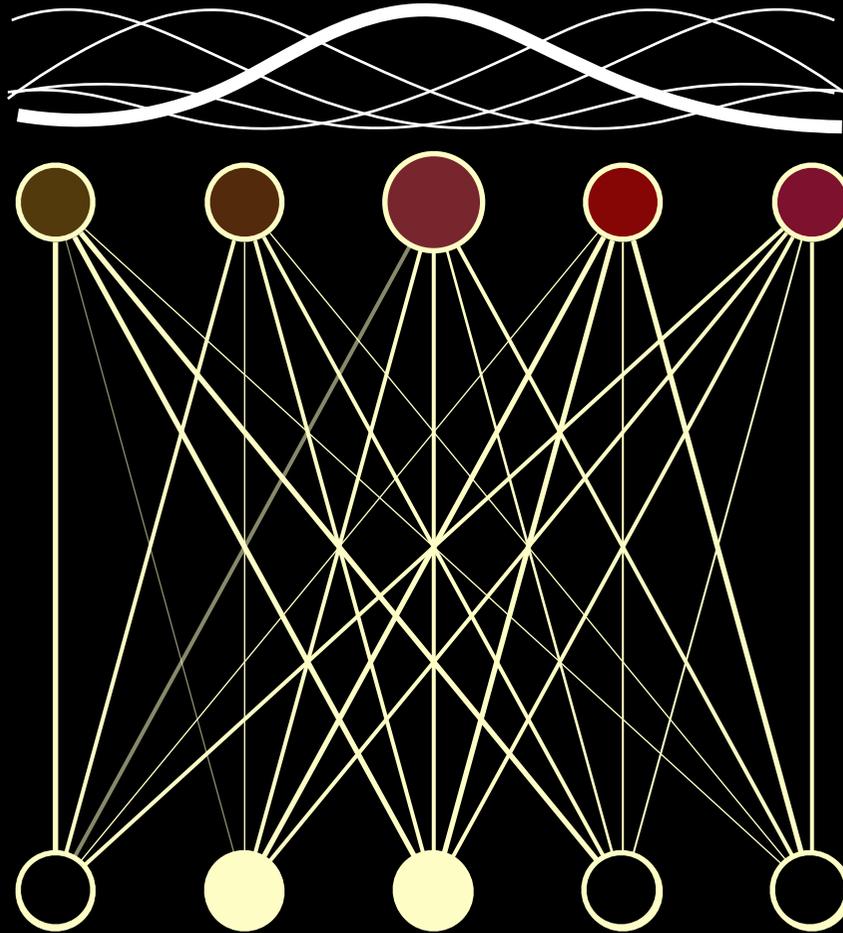


Self-Organizing Maps



Self-Organizing Maps

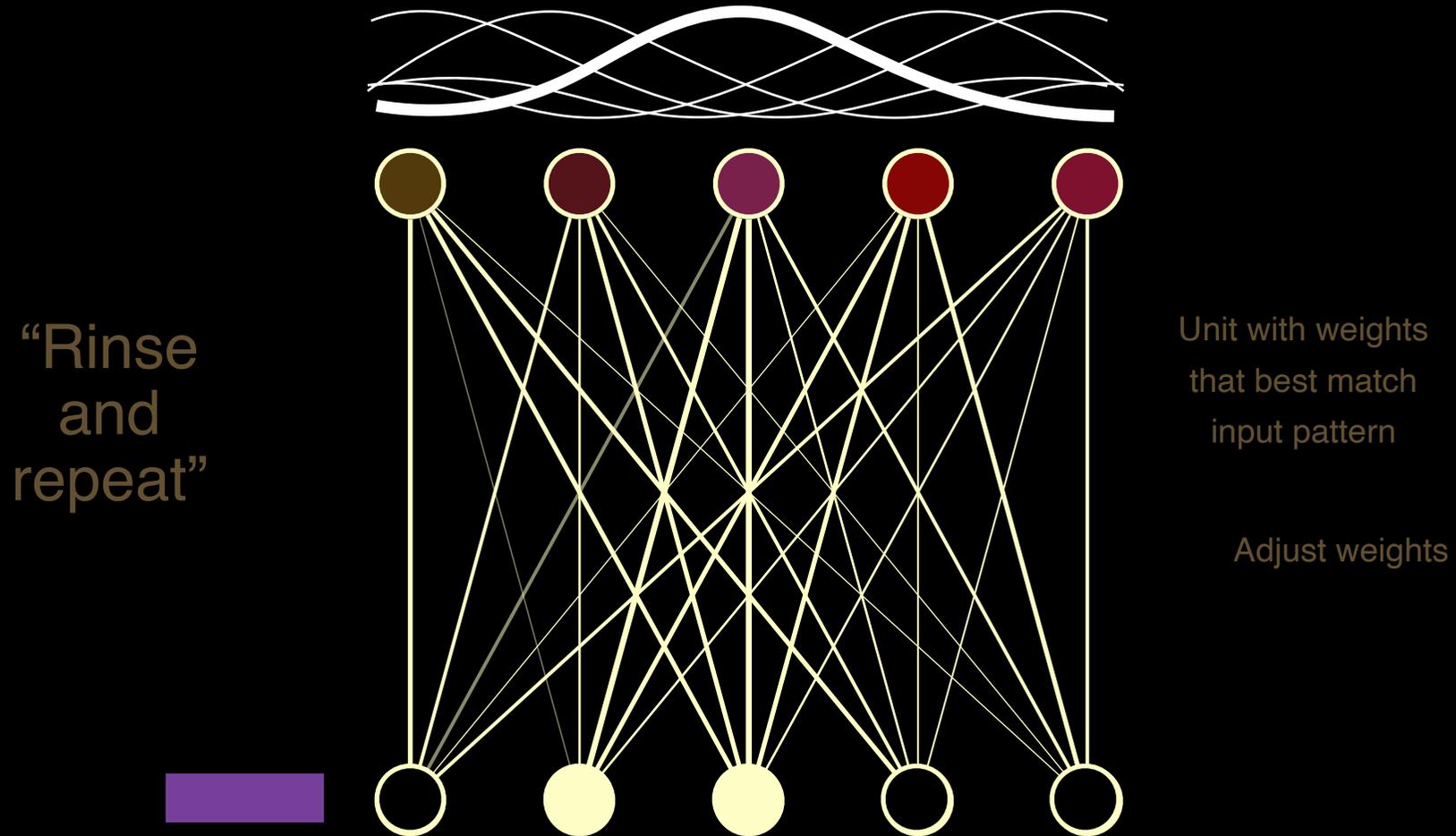
“Rinse
and
repeat”



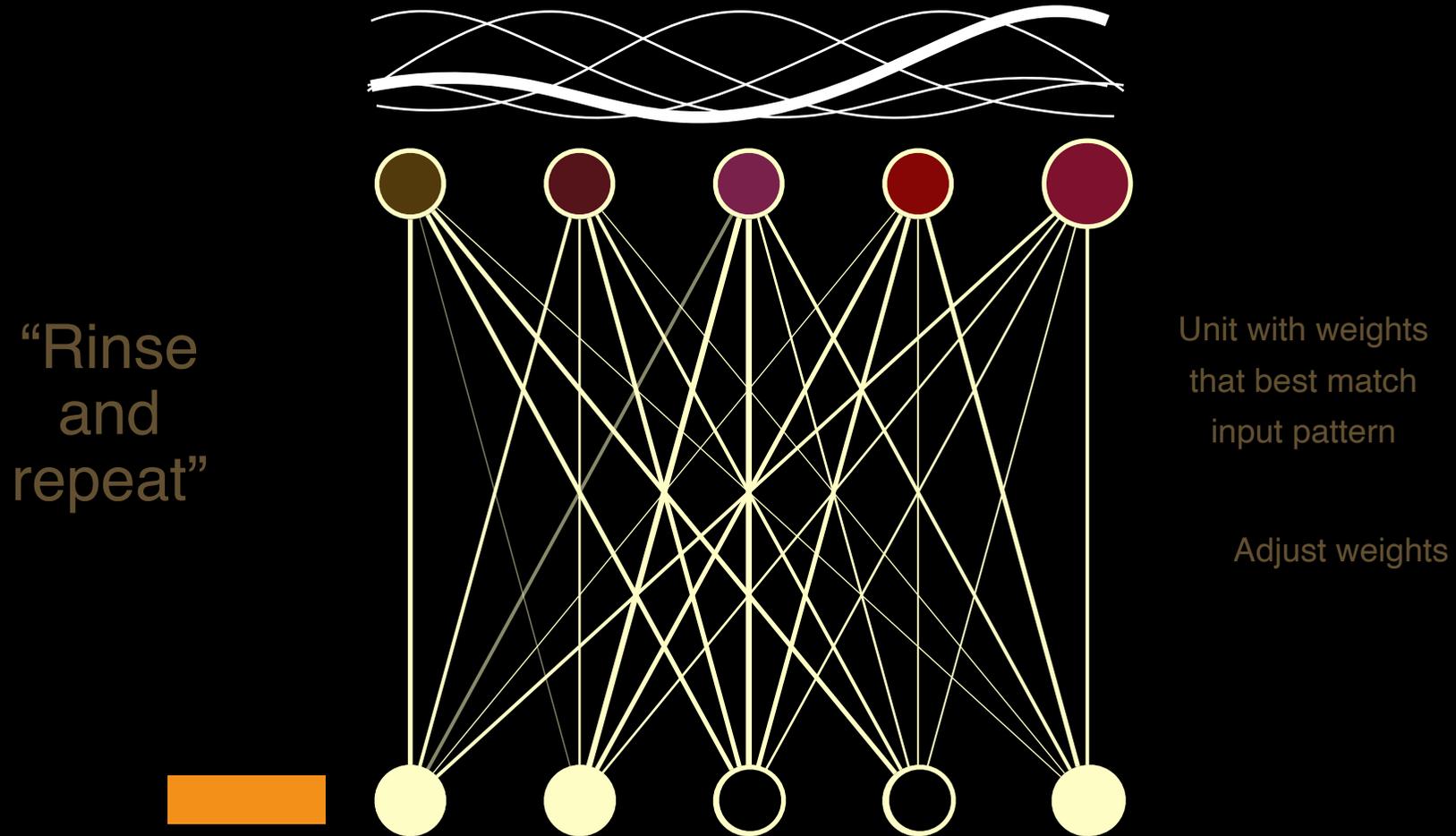
Unit with weights
that best match
input pattern

Adjust weights

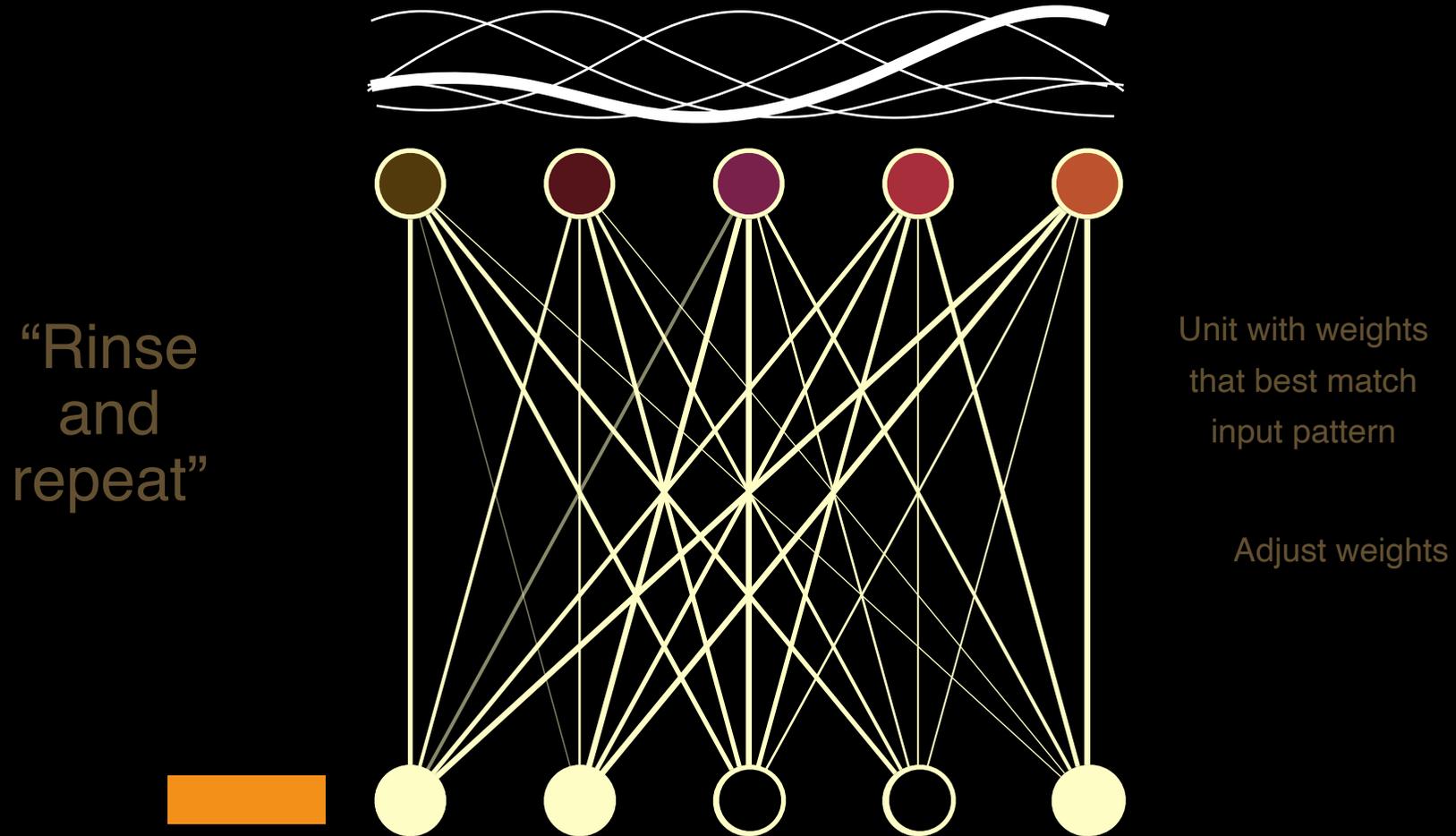
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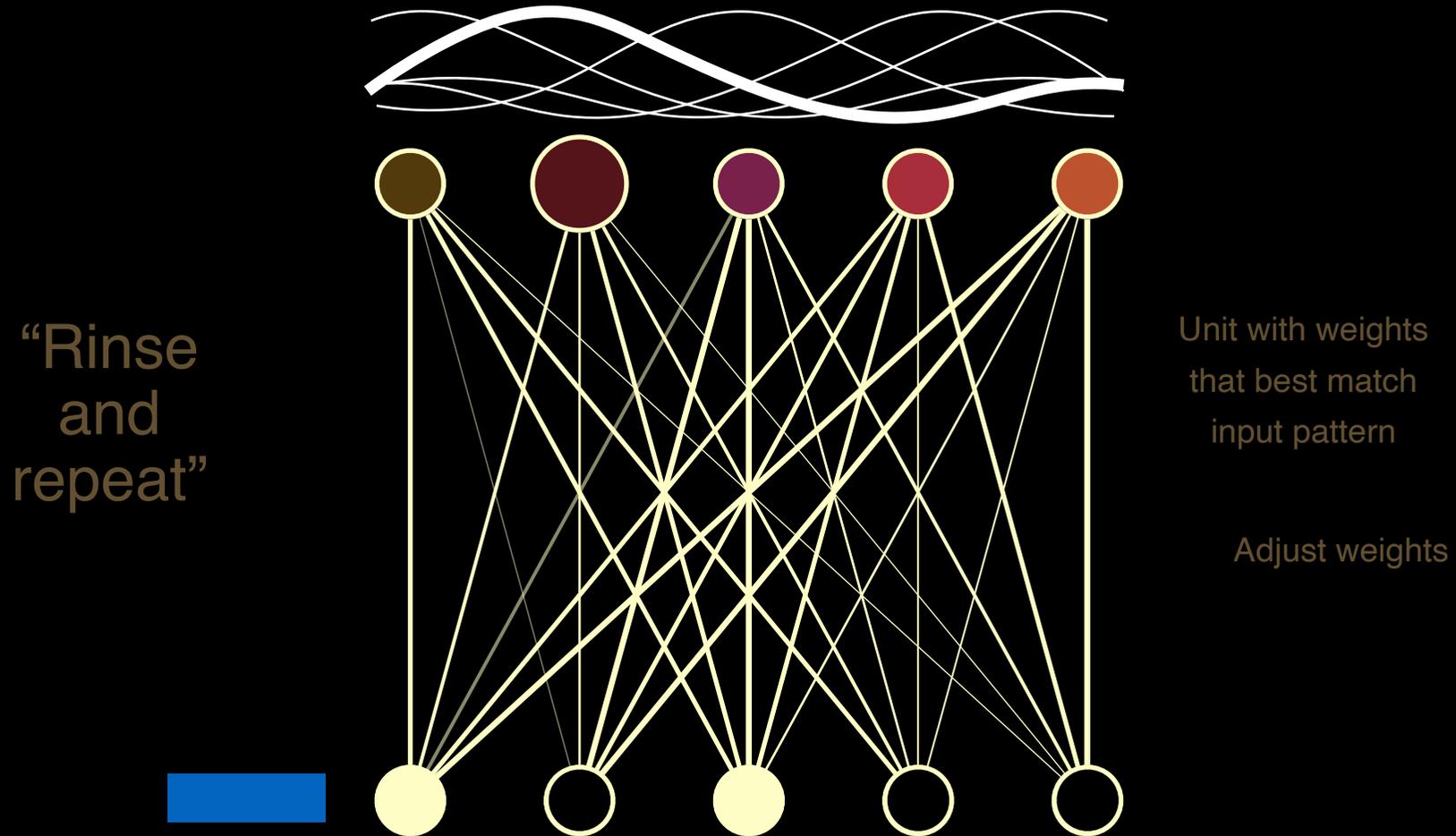
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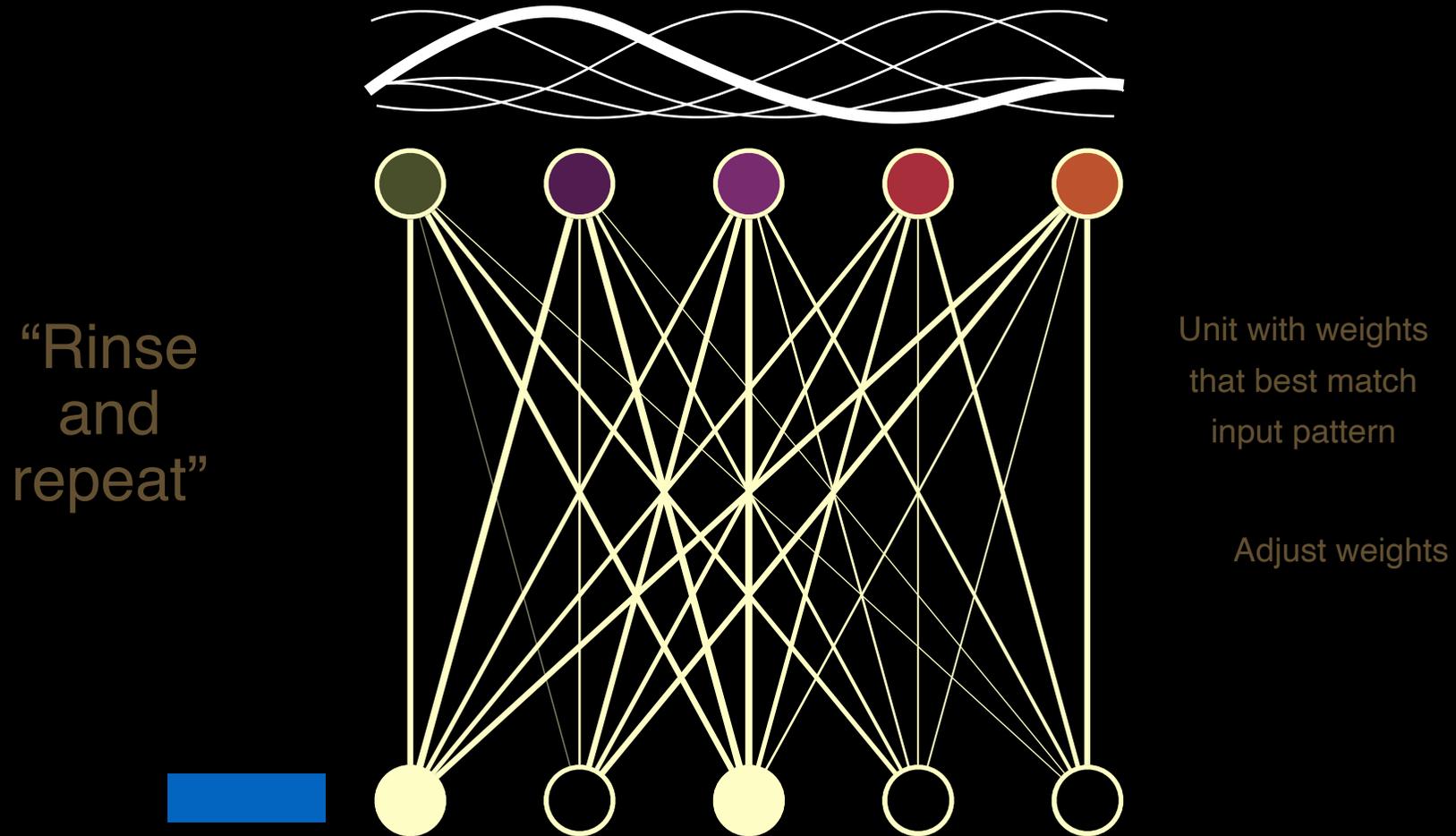
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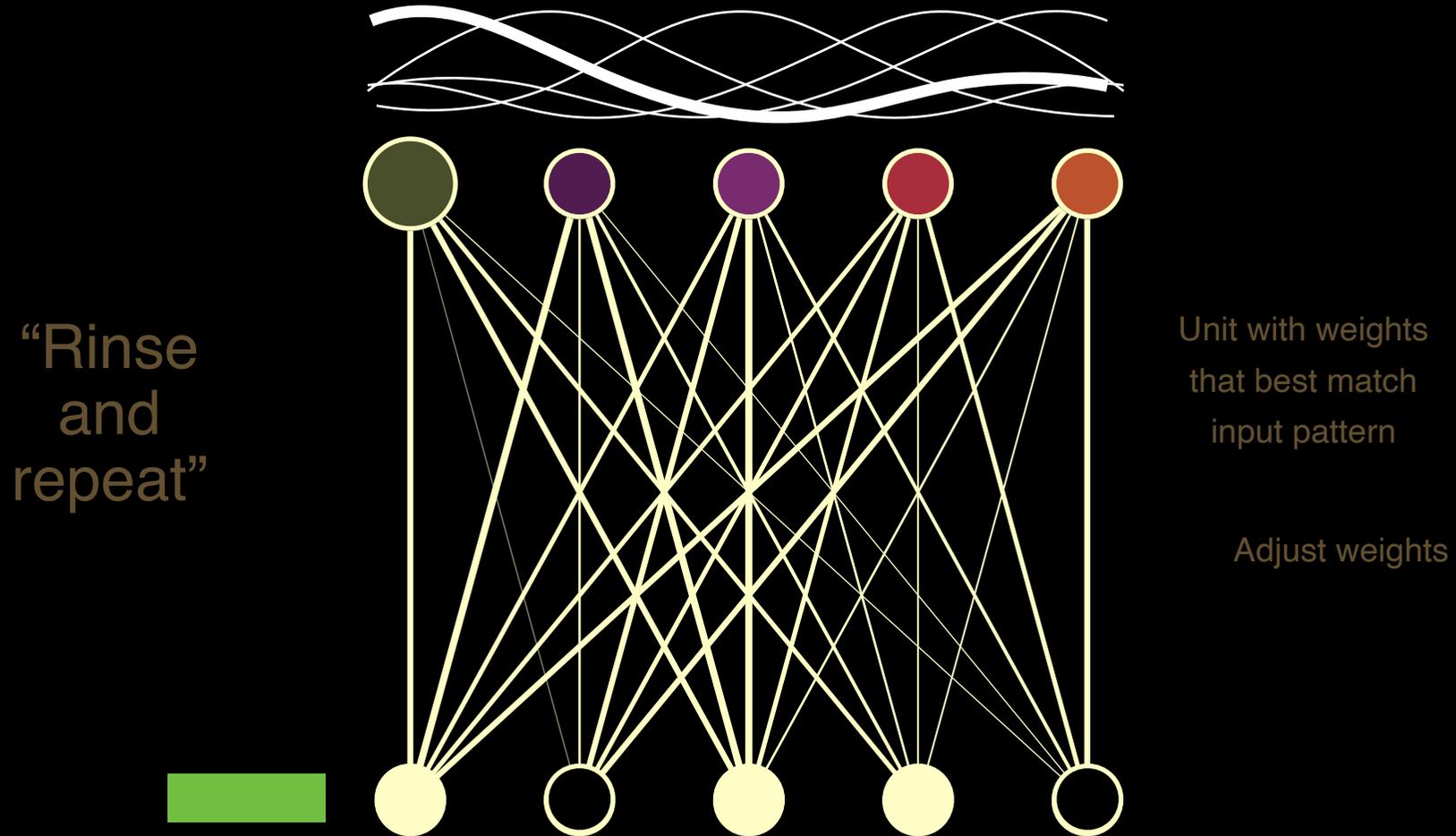
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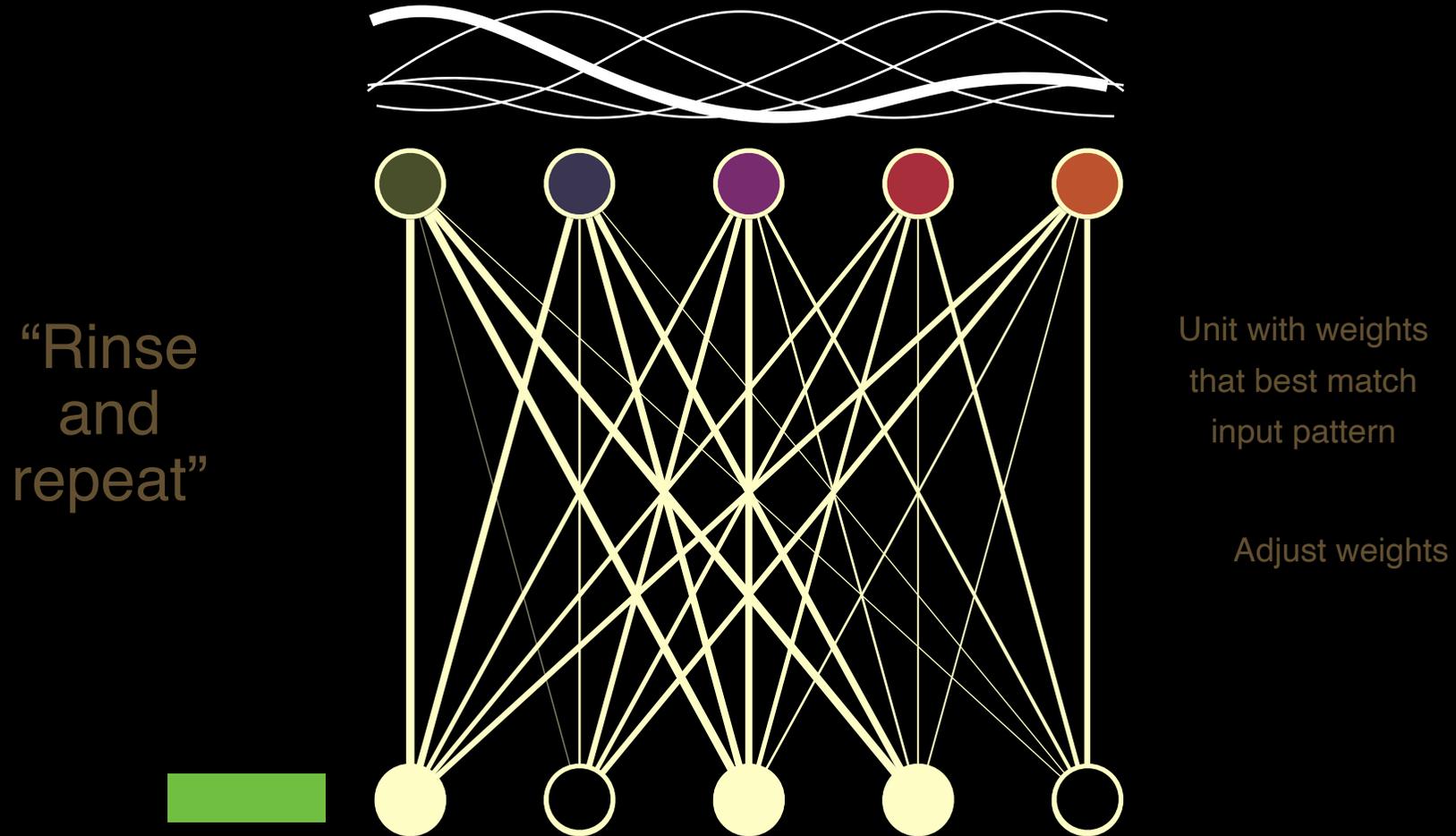
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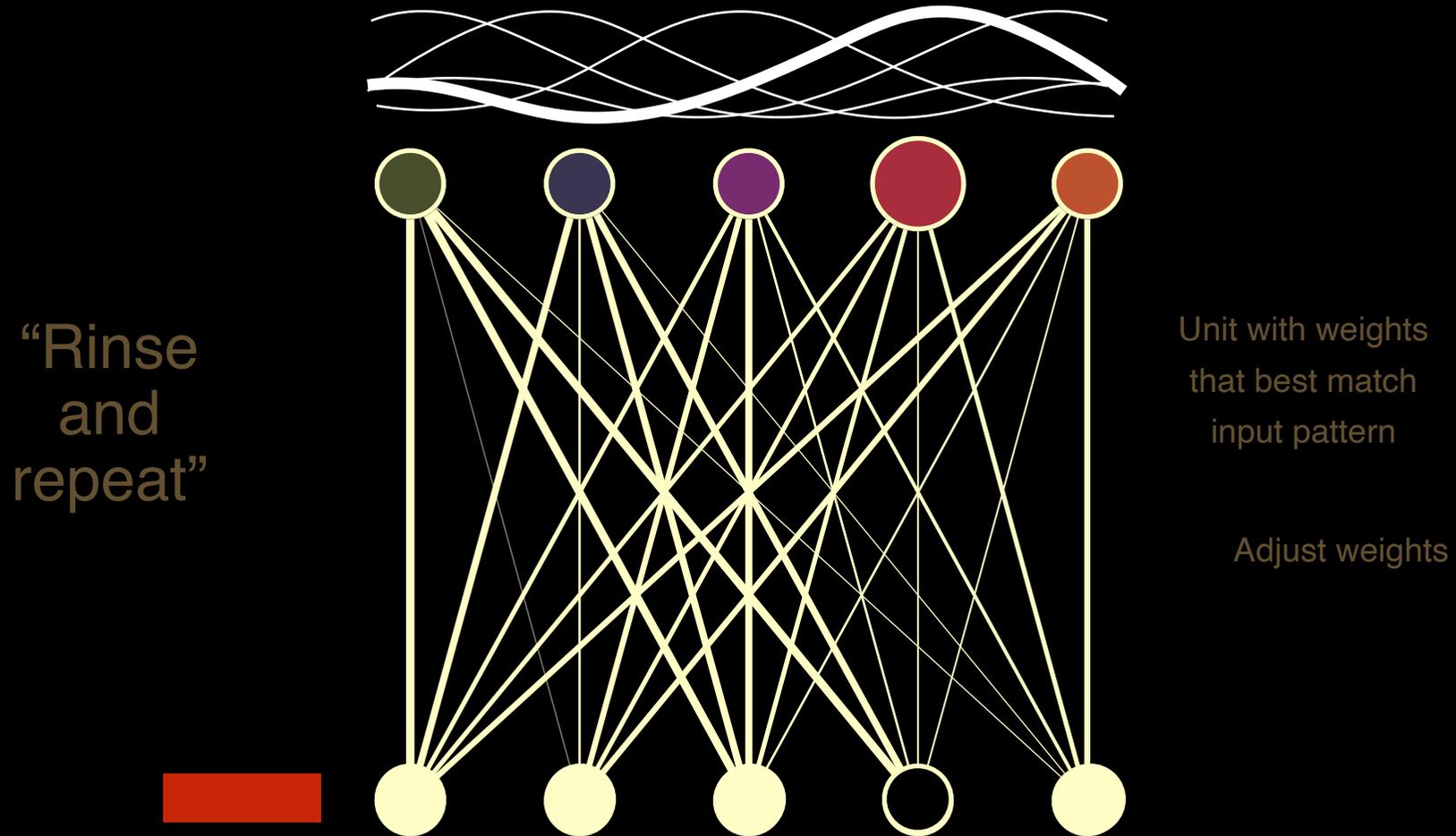
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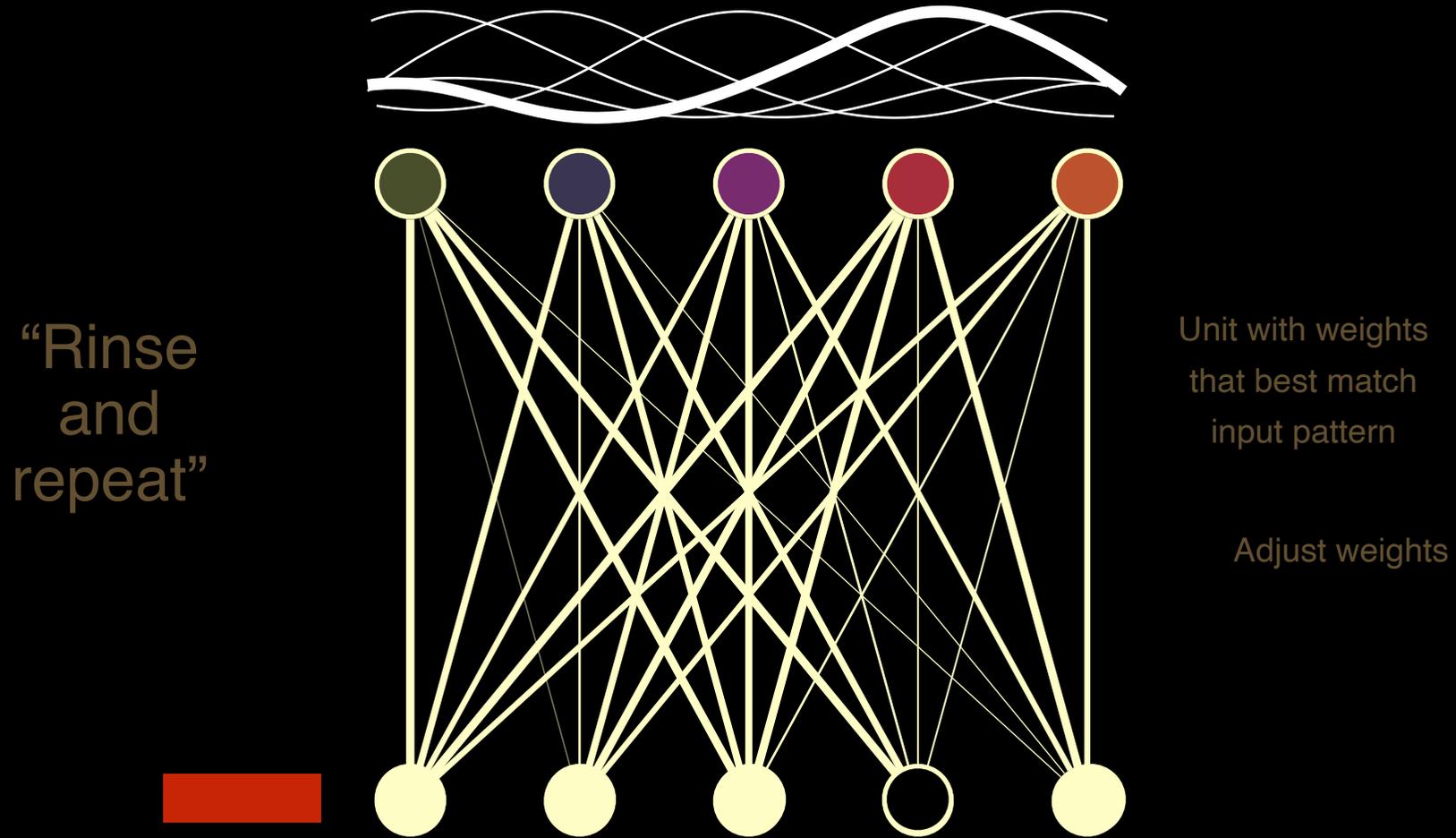
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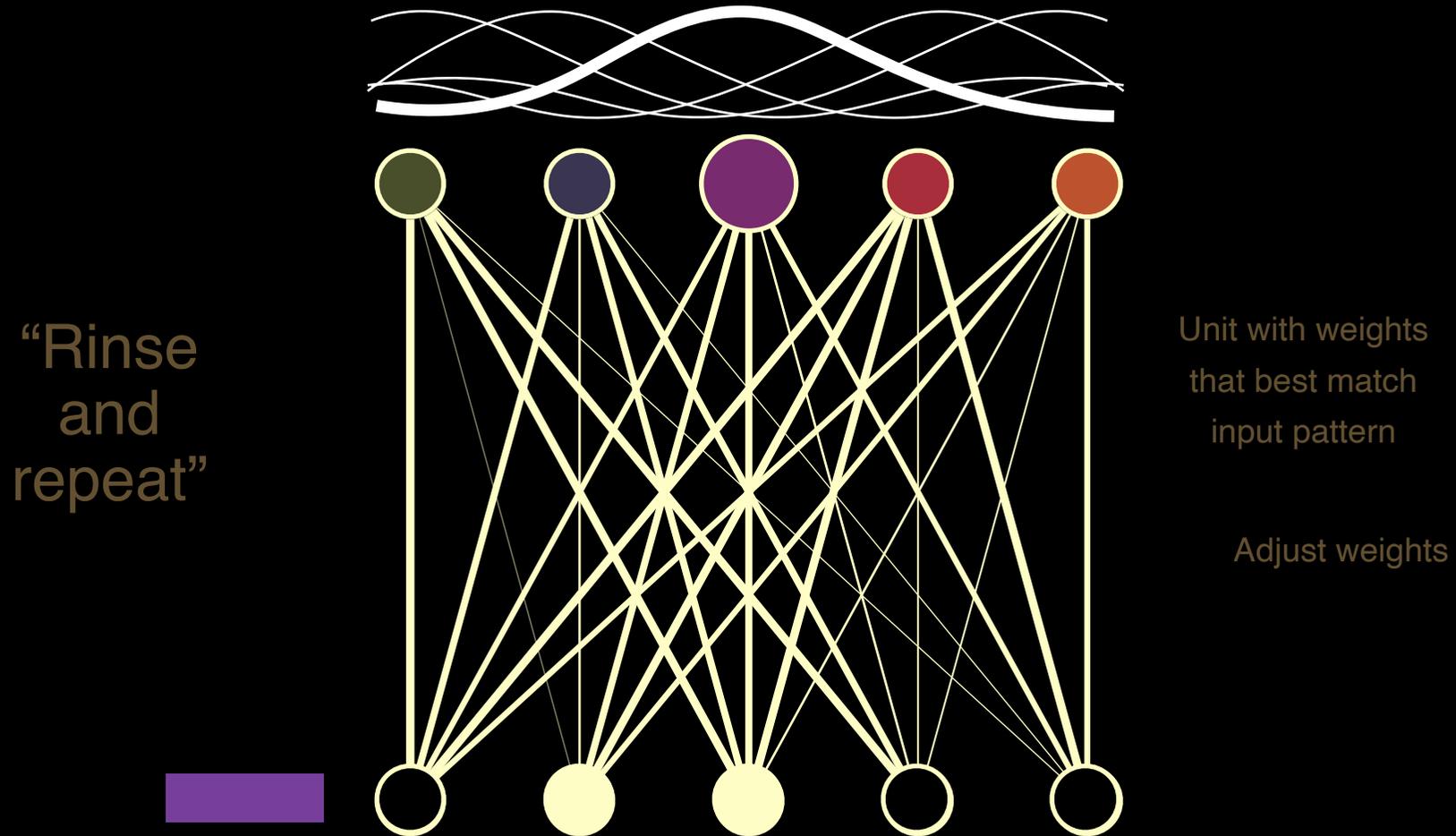
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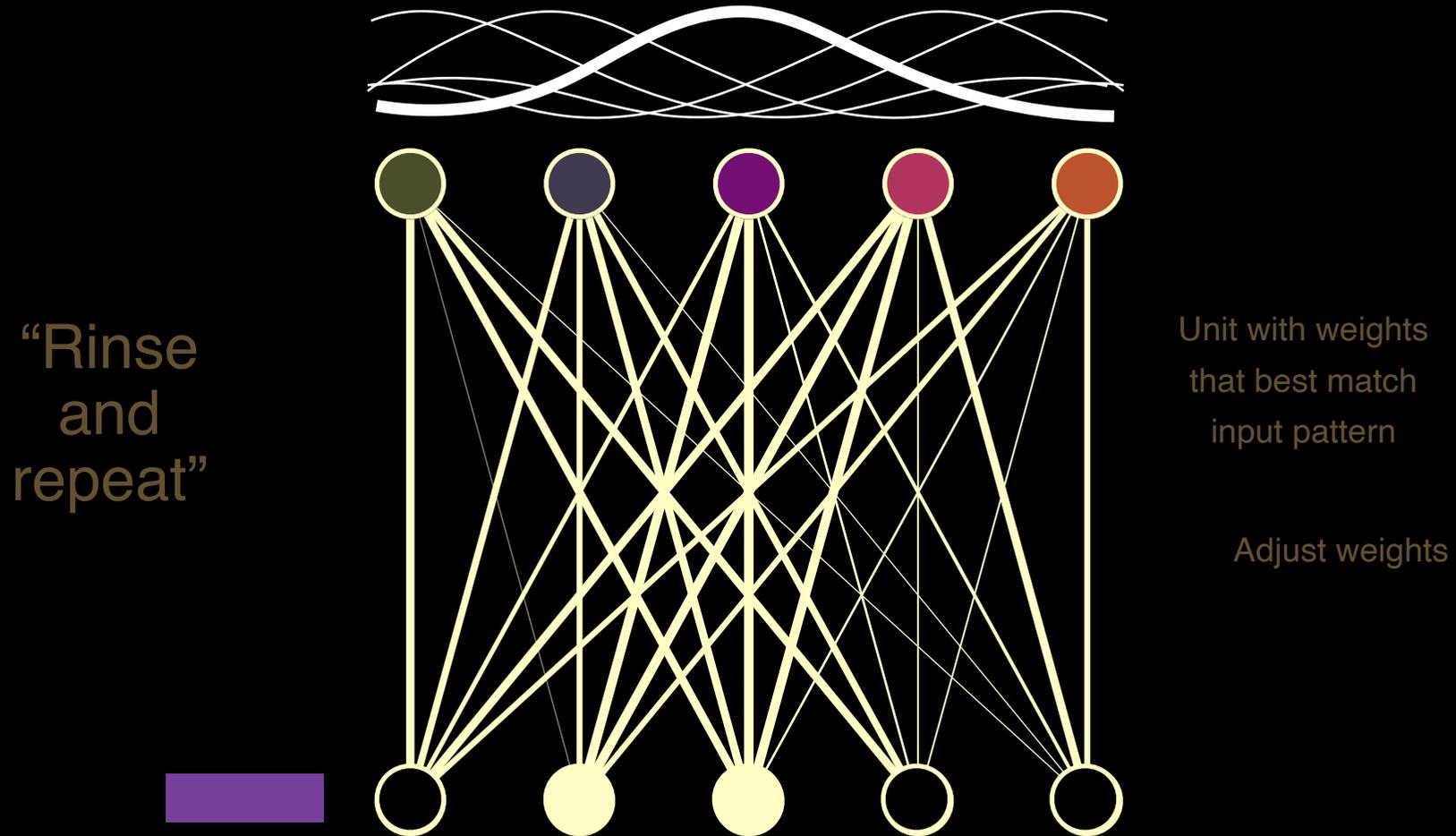
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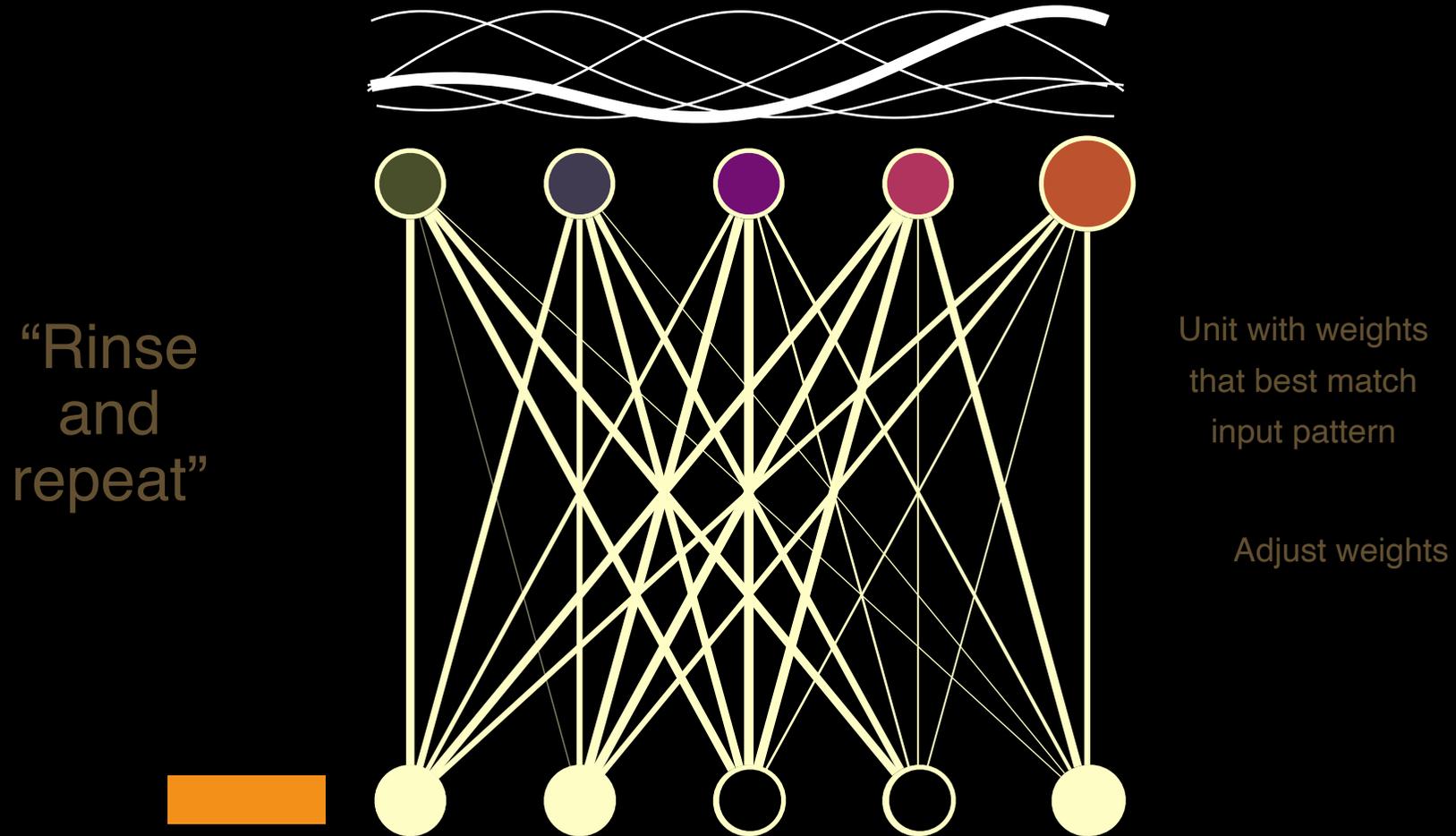
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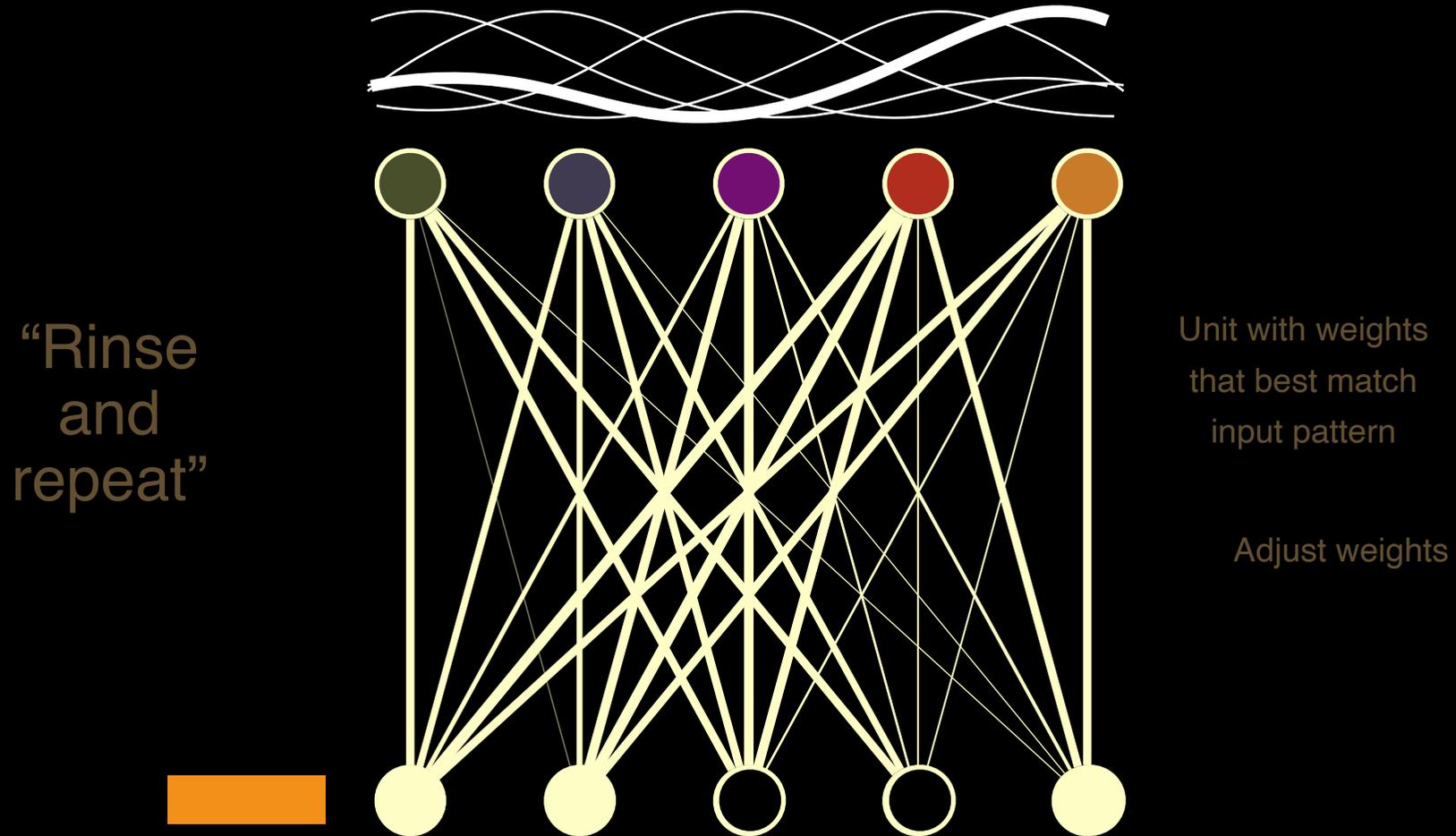
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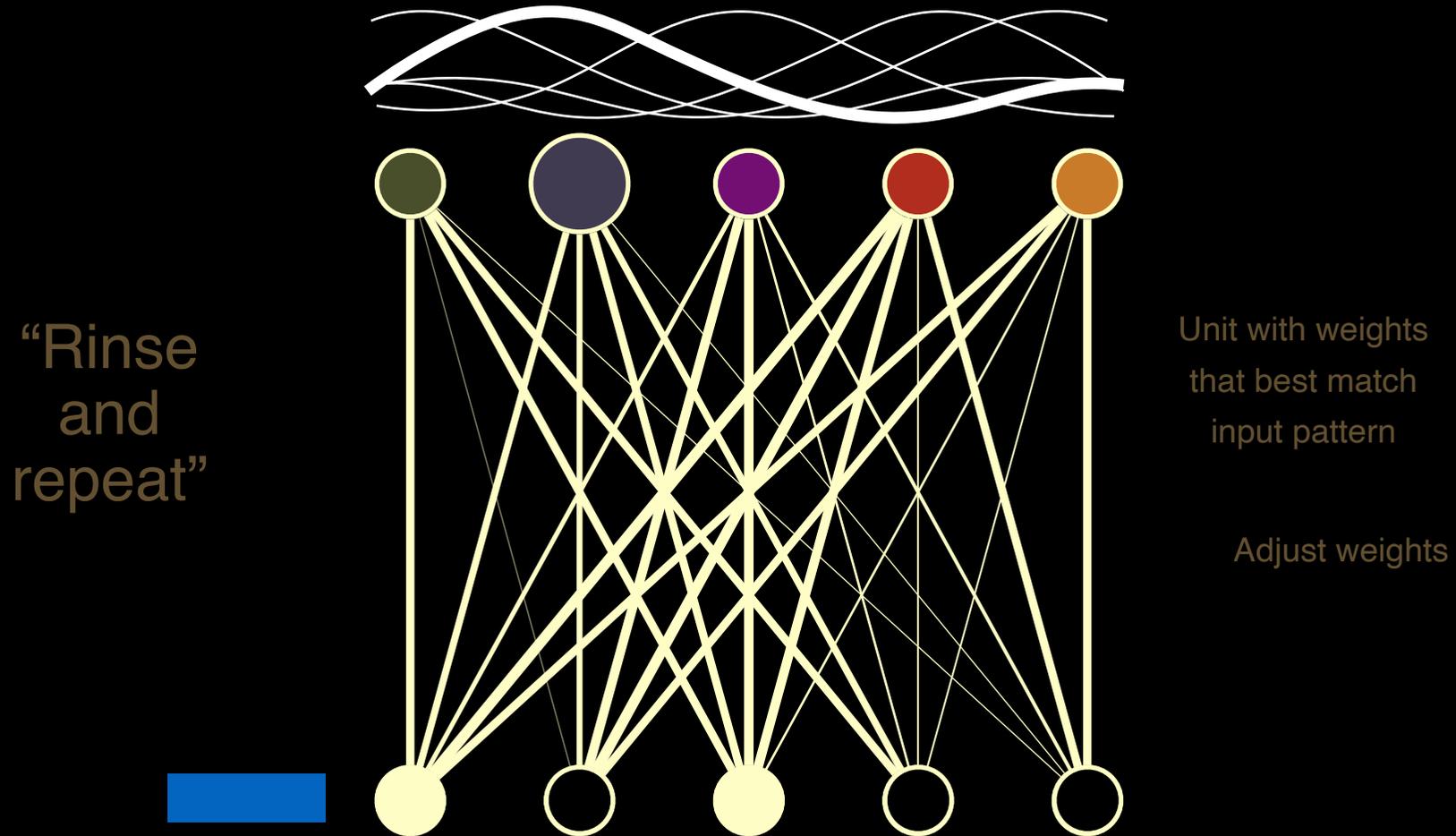
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